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NONLINEAR MAGNETIC CIRCUIT ANALYSIS FOR A NOVEL STATOR-DOUBLY-FED DOUBLY-SALIENT MACHINE

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<u>Purpose</u>

doubly-salient permanent-magnet (DSPM) machine takes the advantages of high power density and high efficiency, but still suffers from limited constant-power speed range and high PM material cost [1]. This paper proposes a novel topology, namely the stator-doubly-fed doubly-salient (SDFDS) machine, which not only solves the problems of the DSPM machine, but also offers the flexibility to on-line optimize the efficiency. In order to effectively analyze and efficiently optimize the proposed machine, a new nonlinear magnetic circuit (NMC) analysis approach is also proposed.

Proposed topology

As shown in Fig.1, the proposed machine consists of two types of stator windings polyphase armature winding and dc field winding. The polyphase armature winding operates like that for a DSPM machine, whereas the field winding not only works as an electromagnet but also as a tool for flux weakening and/or flux optimization.

Proposed analysis

A NMC model is proposed for effective analysis and efficient optimization of the SDFDS machine as shown in Fig.2, in which the non-idealities in both the airgap and pole permeances are also taken into account. The resulting static characteristics, including back EMF (Fig.3), self-inductance and mutual inductance, are verified by experimentation.

[1] M. Cheng, K.T. Chau and C.C. Chan, "Design and analysis of a new doubly salient permanent magnet motor," IEEE Trans Magnetics, 2001, pp. 3012-3020.

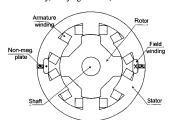


Fig.1. Proposed SDFDS machine topology.

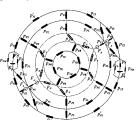
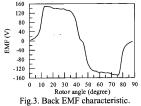


Fig.2. Proposed NMC model.



COGGING TORQUE MINIMIZATION FOR SMALL SPINDLE MOTOR THROUGH REDUCED-ORDER FINITE ELEMENT OPTIMIZATION

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Introduction

The optimization objective is to find a combination of magnet parameters (radial length, magnetic strength) which minimizes the cogging effect in a spindle motor (Figure 1). Reduced order finite element technique provides an accurate means to predict the cogging effect while keeping computational overhead low.

Reduced-Order Formulation

Reduced-order finite element formulation [1] reduces computation time by extrapolating a new solution of vector potential A from a solution set previously obtained (for various parameter combinations) when small changes to magnet parameters are made in the optimization iteration process. The problem then reduces to solving the linear system $A_N u_N = b_N$ with $A_N = W_N^T A_n W_N$, $b_N = W_N^T b_n$. u_n is the original norder A vector (finite element problem with n nodes), u_N the reduced order A vector, and W_N is the $n \times N$ set of previously calculated solutions of A. The computation is faster as it involves lower order matrix computation. The A values are then used to obtain the torque value [2] and the process repeated until a combination of magnet parameters is found to minimize the cogging torque. Typical torque profiles for various magnet properties are shown in Figure 2.

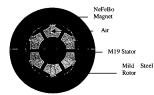


Figure 1: Spindle Motor Structure

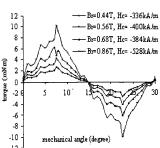


Figure 2: Cogging torque or visious magnet types

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