

A multivariate random-parameters Tobit model for analyzing highway crash rates by injury severity

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ABSTRACT

In this study, a multivariate random-parameters Tobit model is proposed for the analysis of crash rates by injury severity. In the model, both correlation across injury severity and unobserved heterogeneity across road-segment observations are accommodated. The proposed model is compared with a multivariate (fixed-parameters) Tobit model in the Bayesian context, by using a crash dataset collected from the Traffic Information System of Hong Kong. The dataset contains crash, road geometric and traffic information on 224 directional road segments for a five-year period (2002-2006). The multivariate random-parameters Tobit model provides a much better fit than its fixed-parameters counterpart, according to the deviance information criteria and Bayesian R^2 , while it reveals a higher correlation between crash rates at different severity levels. The parameter estimates show that a few risk factors (bus stop, lane changing opportunity and lane width) have heterogeneous effects on crash-injury-severity rates. For the other factors, the variances of their random parameters are insignificant at the 95 % credibility level, then the random parameters are set to be fixed across observations. Nevertheless, most of these fixed coefficients are estimated with higher precisions (i.e., smaller variances) in the random-parameters model. Thus, the random-parameters Tobit model, which provides a more comprehensive understanding of the factors' effects on crash rates by injury severity, is superior to the multivariate Tobit model and should be considered a good alternative for traffic safety analysis.

Keywords: Crash rate by severity; Random parameters; Multivariate Tobit model; Bayesian inference.

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1

2 **1. Introduction**

3

4 In the field of traffic safety analysis, considerable research effort has been devoted
5 to the application of innovative methodological approaches to model crash frequency.
6 Because crash frequencies are non-negative integers, most of the advanced
7 approaches are based on the basic statistical count model, Poisson regression, while
8 addressing certain issues related to crash-frequency data (e.g., over-dispersion,
9 under-dispersion, excess zero observations, spatiotemporal correlation, multilevel
10 structure, and unobserved heterogeneity). [Lord and Mannering \(2010\)](#) and [Mannering
11 and Bhat \(2014\)](#) presented overviews of these models.

12 Recently, as good alternatives to the traditional crash-frequency approaches,
13 methods for analyzing crash rates (such as the number of crashes per 100 million
14 vehicle miles traveled) have been developed in a number of studies ([Anastasopoulos
15 et al., 2008](#); [Caliendo et al., 2015](#)). Neutralizing the effects of crash exposure, the
16 crash rates forms a standardized measure of the relative safety performance of
17 roadway sites (e.g., roadway segments and intersections), which is more acceptable
18 for the public than the crash frequency. Meanwhile, the crash rate is able to clearly
19 reflect the risk of involving in a crash and thus may be a more effective criterion for
20 the identification of hotspots ([Ma et al., 2015b](#); [Xu et al., 2014](#)). Moreover, crash rates
21 are commonly used in accident reporting systems, such as the annual crash reports of
22 the National Highway Traffic Safety Administration ([NHTSA, 2012](#)). Therefore, the
23 crash rate may sometimes be preferable to the crash frequency.

24 From the perspective of statistical modeling, crash rates are continuous,
25 non-negative numbers, which differ substantially from (discrete integers) crash
26 frequencies. Crash-rate data are usually left-censored at zero because no crashes may
27 be observed at several sites during certain periods. Censoring refers to a limitation on
28 data clustering which may result in a lower threshold (left-censored), an upper
29 threshold (right-censored), or both. The censoring phenomenon in crash rates may
30 appear for two distinct reasons, including a lack of crashes at the sites over the
31 observation period and a failure to report crashes that occur ([Anastasopoulos et al.,
32 2012a](#)). Generally, more severe crashes are more likely to be reported ([Lord and
33 Mannering, 2010](#)). To deal with the censoring characteristic, [Anastasopoulos et al.
34 \(2008\)](#) first introduced the Tobit model to analyze crash rates. Various forms of
35 random-parameter Tobit models have since been proposed to account for unobserved
36 heterogeneity across observations ([Anastasopoulos et al., 2012a](#); [Caliendo et al., 2015](#);
37 [Ma et al., 2015a](#); [Yu et al., 2015](#)). The Tobit-based (crash rate prediction) models
38 avoid some shortcomings associated with Poisson-based (crash frequency prediction)
39 models, such as the requirement of equal mean and variance of Poisson distribution
40 and the hypothesized zero state in the zero-inflated count models ([Lord et al., 2005,
41 2007](#)), which may be a potentially technical advantage of crash rate modeling over
42 crash frequency modeling.

1 Compared with analysis of the total crash rate, modeling the crash rate by injury
2 severity can illustrate the effects of observed risk factors (such as the traffic,
3 geometric, and environmental characteristics of sites) on the crash rate with a
4 particular injury-severity outcome. The expected crash rates at each level of severity
5 provide deeper insight into the safety situation of a certain road site. Therefore,
6 although the overall crash rate may not reveal a site deficiency, overexposure of a
7 specific crash severity may uncover otherwise undetected deficiencies. Moreover,
8 models for the analysis of crash-injury-severity rates may be more appealing for
9 ranking road sites that hold promise for safety improvement, because injury severity
10 and the associated costs are the primary concerns in many programs (Miaou and Song,
11 2005). However, only two existing studies (Anastasopoulos et al., 2012b; Xu et al.,
12 2014) have focused on jointly modeling crash rates by injury severity. Their model
13 estimation results support the notion that a significant correlation exists between crash
14 rates at various severity levels, which may be a result of common unobserved factors
15 that affect crash rates across injury severity. Similarly, significant correlations among
16 crash frequencies by injury severity or crash type have already been demonstrated in
17 many multivariate count models (Aguero-Valverde and Jovanis, 2009; Barua et al.,
18 2014; Bijleveld, 2005; El-Basyouny and Sayed, 2009; El-Basyouny et al., 2014; Ma
19 and Kockelman, 2006; Ma et al., 2008; Park and Lord, 2007). Nonetheless, the fixed
20 parameters in all these studies omit the potential heterogeneity in the effects of risk
21 factors across observations, which have been found in the previous research using
22 random-parameters models to analyze total crash rate (Anastasopoulos et al., 2012a),
23 total crash frequency (Anastasopoulos and Mannering, 2009) and crash frequencies
24 by severity (Barua et al., 2016). Ignoring the possible heterogeneity across
25 observations and constraining the parameters to be constant, such fixed parameters
26 models would lead to biased parameters and incorrect inferences (Washington et al.,
27 2011). As noted by Anastasopoulos et al. (2012b), the inclusion of random parameters
28 in the multivariate Tobit model would be able to capture the unobserved
29 heterogeneity.

30 To this end, the main objective of this study is to develop a multivariate
31 random-parameters Tobit model for the simultaneous analysis of crash rates by injury
32 severity that accounts for both correlations between crash rates at different severity
33 levels and the variations in the effects of risk factors across observations. To
34 demonstrate the proposed model, it is compared to a multivariate (fix-parameters)
35 Tobit model in the Bayesian context using crash-injury-severity-rate data on road
36 segments in Hong Kong over a 5-year period. Accordingly, the remainder of this
37 paper is organized as follows. The next section specifies the proposed models and
38 criteria for model comparison. The collected data for model demonstration are
39 described in Section 3. Section 4 introduces the detailed estimation of the proposed
40 models and discusses the parameter estimation results. Finally, conclusions and
41 recommendations for future research are presented in Section 5.

42

2. Methods

In this section, the formulations of the two candidate models for the simultaneous analysis of crash-injury-severity rates, multivariate Tobit and multivariate random-parameters Tobit regressions, are first specified explicitly under the Bayesian framework. Two criteria in the context of Bayesian inference, the deviance information criteria (DIC) and Bayesian R^2 , are then introduced for the purpose of model comparison.

2.1. Model specification

2.1.1. Multivariate Tobit model

As mentioned, crash rates are generally left-censored at zero, because crashes may not be reported at some sites during the study period. The Tobit regression, first proposed by James Tobin (1958), is an appropriate method for the analysis of censored data (Anastasopoulos et al., 2008). To accommodate the possible correlation between crash rates at various severity levels, a multivariate Tobit model was advocated by Anastasopoulos et al. (2012b). Using a left-censored threshold of zero, the multivariate Tobit regression for the joint modeling of the crash rate by injury severity is expressed as follows:

$$Y_{it}^{k*} = \beta_{k0} + \sum_{m=1}^M \beta_{km} x_{it}^m + \varepsilon_{it}^k, \quad (1)$$

$$Y_{it}^k = \begin{cases} Y_{it}^{k*}, & \text{if } Y_{it}^{k*} > 0 \\ 0, & \text{if } Y_{it}^{k*} \leq 0 \end{cases}, \quad i = 1, 2, \dots, N, \quad t = 1, 2, \dots, T, \quad k = 1, 2, \dots, K, \quad (2)$$

where Y_{it}^{k*} and Y_{it}^k represent the unobservable and observed crash rate at injury severity level k and site i during period t , respectively. N , T and K are the number of the observed sites, periods and categorized injury severity levels respectively. $x_{it}^1, x_{it}^2, \dots, x_{it}^M$ are the observed values of M risk factors at site i during period t , while $\beta_{k1}, \beta_{k2}, \dots, \beta_{kM}$ are the estimable coefficients corresponding to injury severity level k . β_{k0} is the constant, and ε_{it}^k denotes the random error term which is assumed to follow a multi-normal distribution with zero mean, that is,

$$\boldsymbol{\varepsilon}_{it} \sim N_K(\mathbf{0}, \boldsymbol{\Sigma}), \quad \boldsymbol{\varepsilon}_{it} = \begin{pmatrix} \varepsilon_{it}^1 \\ \varepsilon_{it}^2 \\ \dots \\ \varepsilon_{it}^K \end{pmatrix}, \quad \boldsymbol{\Sigma} = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \dots & \sigma_{1K} \\ \sigma_{21} & \sigma_{22} & \dots & \sigma_{2K} \\ \dots & \dots & \dots & \dots \\ \sigma_{K1} & \sigma_{K2} & \dots & \sigma_{KK} \end{pmatrix}. \quad (3)$$

1 In Eq. (3), σ_{kk} ($k = 1, 2, \dots, K$) represents the variance of error term ε_{it}^k and σ_{k_1, k_2}
 2 ($k_1 \neq k_2$) denotes the covariance between $\varepsilon_{it}^{k_1}$ and $\varepsilon_{it}^{k_2}$.

3

4 2.1.2. Multivariate random-parameters Tobit model

5 Studies have demonstrated that heterogeneous effects of certain factors may be
 6 present across observations of the total crash rate (Anastasopoulos et al., 2012a;
 7 Caliendo et al., 2015; Ma et al., 2015a; Yu et al., 2015). A random-parameters Tobit
 8 model is the prevalent approach applied to deal with this issue. It is reasonable to
 9 speculate that this phenomenon may also exist in crash-injury-severity rate analysis.
 10 Therefore, to accommodate the underlying unobserved heterogeneity in the
 11 multivariate Tobit model, the coefficients ($\beta_{k0}, \beta_{k1}, \dots, \beta_{kM}$) in Eq. (1) are set to be
 12 random parameters ($\beta_{it}^{k0}, \beta_{it}^{k1}, \dots, \beta_{it}^{kM}$):

$$13 \quad Y_{it}^{k*} = \beta_{it}^{k0} + \sum_{m=1}^M \beta_{it}^{km} x_{it}^m + \varepsilon_{it}^k. \quad (4)$$

14 Because $\beta_{it}^{1m}, \beta_{it}^{2m}, \dots, \beta_{it}^{Km}$ may be also correlated, suggested by Barua et al. (2016),
 15 they are assumed to be multi-normally distributed as:

$$16 \quad \beta_{it}^m \sim N_K(\boldsymbol{\beta}_m, \boldsymbol{\Sigma}_m), \quad \beta_{it}^m = \begin{pmatrix} \beta_{it}^{1m} \\ \beta_{it}^{2m} \\ \dots \\ \beta_{it}^{Km} \end{pmatrix}, \quad \boldsymbol{\Sigma}_m = \begin{pmatrix} \sigma_{11}^m & \sigma_{12}^m & \dots & \sigma_{1K}^m \\ \sigma_{21}^m & \sigma_{22}^m & \dots & \sigma_{2K}^m \\ \dots & \dots & \dots & \dots \\ \sigma_{K1}^m & \sigma_{K2}^m & \dots & \sigma_{KK}^m \end{pmatrix}, \quad m = 0, 1, \dots, M, \quad (5)$$

17 in which $\boldsymbol{\beta}_m$ and $\boldsymbol{\Sigma}_m$ are the mean vector and variance-covariance matrix of β_{it}^m
 18 respectively. Noticeably, if the covariance of two random parameters is statistically
 19 insignificant (say, at the 95 % credibility level), they are assumed to follow
 20 independent normal distributions (Barua et al., 2016). If the variance of a certain
 21 random parameter is not statistically significant (say, at the 95 % credibility level), the
 22 random parameter is simplified to be fixed across observations (Anastasopoulos et al.,
 23 2012a).

24

25 2.2. Model comparison

26 As in many other studies that included modeling under the Bayesian framework
 27 (Dong et al., 2014; Huang et al., 2016a; Zeng and Huang, 2014), the DIC and
 28 Bayesian R^2 are used to compare the above candidate models.

29 The DIC is intended as a Bayesian generalization of Akaike's information criteria,
 30 which penalizes larger-parameter models. Specifically, it provides a Bayesian measure

1 of model complexity and fitting and is defined as (Spiegelhalter et al., 2002):

$$2 \quad DIC = \overline{D(\theta)} + pD, \quad (6)$$

3 where $\overline{D(\theta)}$ is the posterior mean deviance that can be taken as a Bayesian measure
4 of fitting, and pD is a complexity measure for the effective number of parameters.
5 Generally, models with lower DIC values are preferred. However, it is worth noting
6 that determination of a critical difference in DIC is very difficult. According to
7 Spiegelhalter et al. (2005), very roughly, more than 10 differences may rule out the
8 model with the higher DIC; differences between 5 and 10 are considered substantial;
9 and if the DIC difference is less than 5, and the model inferences are significantly
10 different, it could be misleading to simply report the model with the lowest DIC.

11 The Bayesian R^2 measure, which could be viewed as a global model-fit
12 measurement, is proposed to estimate the ratio of the explained sum of squares to the
13 total sum of squares (Ahmed et al., 2011; Zeng and Huang, 2014). To evaluate the
14 model fit comprehensively, the Bayesian R^2 values of crash rates at each injury
15 severity k and all observations, represented by R_k^2 and R_T^2 respectively, are all
16 calculated:

$$17 \quad R_k^2 = 1 - \frac{\sum_{t=1}^T \sum_{i=1}^N (Y_{it}^k - \lambda_{it}^k)^2}{\sum_{t=1}^T \sum_{i=1}^N (Y_{it}^k - \bar{Y}_k)^2}, \quad k = 1, 2, \dots, K, \quad (7)$$

$$18 \quad R_T^2 = 1 - \frac{\sum_{k=1}^K \sum_{t=1}^T \sum_{i=1}^N (Y_{it}^k - \lambda_{it}^k)^2}{\sum_{k=1}^K \sum_{t=1}^T \sum_{i=1}^N (Y_{it}^k - \bar{Y})^2}, \quad (8)$$

$$19 \quad \lambda_{it}^k = \begin{cases} \beta_{k0} + \sum_{m=1}^M \beta_{km} x_{it}^m, & \text{if } \beta_{k0} + \sum_{m=1}^M \beta_{km} x_{it}^m > 0 \\ 0, & \text{if } \beta_{k0} + \sum_{m=1}^M \beta_{km} x_{it}^m \leq 0 \end{cases}, \quad (9)$$

$$20 \quad \bar{Y}_k = \frac{1}{T \times N} \sum_{t=1}^T \sum_{i=1}^N Y_{it}^k, \quad k = 1, 2, \dots, K, \quad (10)$$

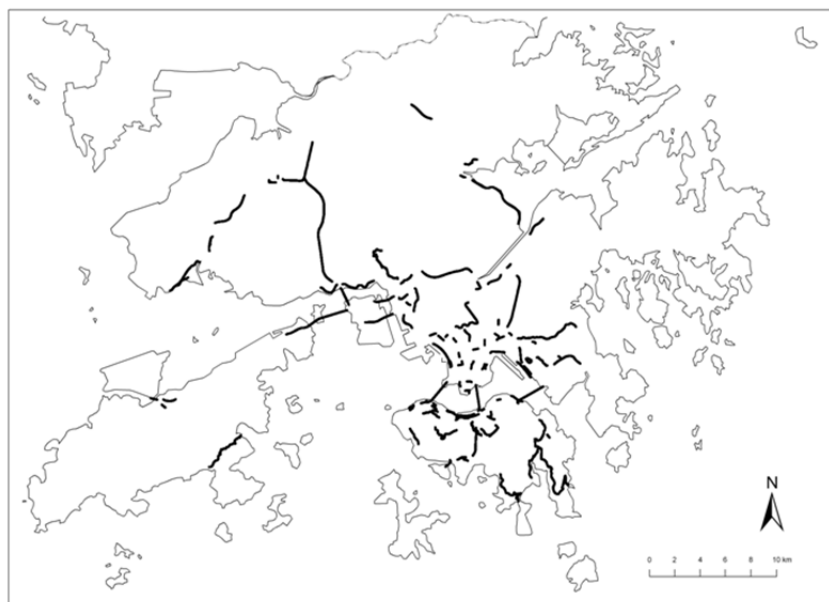
$$21 \quad \bar{Y} = \frac{1}{K \times T \times N} \sum_{k=1}^K \sum_{t=1}^T \sum_{i=1}^N Y_{it}^k. \quad (11)$$

22 In the above equations, λ_{it}^k is the expected crash rates at injury severity level k and
23 site i during period t . \bar{Y}_k and \bar{Y} are the mean of crash rates at injury severity k
24 and all observations, respectively.

26 3. Data preparation and preliminary analysis

1
2 A crash dataset obtained from the Traffic Information System (TIS) maintained by
3 the Transport Department of Hong Kong is used to demonstrate the proposed
4 multivariate random-parameters Tobit model and to compare it with the multivariate
5 Tobit model. This dataset has already been employed in the previous studies on crash
6 frequency prediction (Huang et al., 2016b; Zeng et al., 2016). Therefore, their
7 estimation results could be referred to in this research. It contains 112 road segments
8 with two end points defined by the Hong Kong Annual Traffic Census (ATC) system
9 (as shown in Fig. 1). Their traffic volumes are continuously measured by the 112 core
10 stations of the ATC system. The directional average annual daily traffic (AADT) for
11 each road segment adjacent to the 112 core stations ($N = 224$) from 2002 to 2006
12 ($T = 5$) is derived from the ATC system for the analysis.

13 Geographical information system techniques are used to map crashes to these
14 directional segments, based on the movement attributes of the vehicles involved and a
15 detailed description of each crash recorded in the TIS system. With respect to crash
16 severity, the TIS classifies crashes into three categories – fatal, serious injury, and
17 slight injury – according to the severity of injury among the casualties. Due to the
18 rareness of fatality, it is combined with serious injury to form the category of killed
19 and seriously injured (KSI) crashes ($K = 2$). The road geometric and traffic
20 information is also obtained from the TIS system.



22
23 **Fig. 1.** Selected roadway segments in Hong Kong for the analysis.

24
25 The yearly crash rate (number of crashes per million vehicle-kilometers traveled)
26 by injury severity, CR_{it}^k , which is used as the dependent variable in this study, is
27 calculated as:

$$CR_{it}^k = \frac{No_crash_{it}^k}{AADT_i^t \times L_i \times 365 / 1000,000}, \quad (14)$$

$i = 1, 2, \dots, 224, k = 1, 2, t = 2002, 2003, 2004, 2005, 2006$

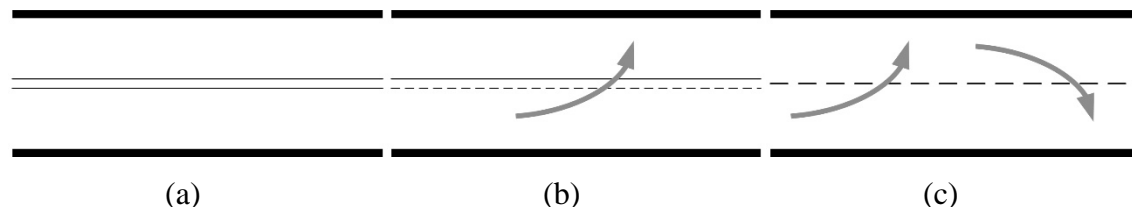
in which $No_crash_{it}^k$ is the number of crashes at injury severity degree k that occurred on road segment i in year t ; $AADT_i^t$ is the AADT on road segment i in year t ; and L_i is the length of segment i , ranging from 0.15 km to 9.07 km with mean 1.47 km. Among the total observations, 76 slight injury crash rates and 349 KSI crash rates are 0. Table 1 illustrates the definitions and descriptive statistics of the variables used in the development of the model. The results of the correlation tests and multi-collinearity diagnoses indicate that there is no significant correlation or collinearity among these factors.

Table 1. Descriptive statistics of the variables.

Variable	Description	Mean	SD	Min.	Max.
<i>Response variable</i>					
Slight	Slightly injured crash count per million vehicle-kilometers traveled	1.70	2.21	0	24.35
KSI	Killed and seriously injured crash count per million vehicle-kilometers traveled	0.46	0.98	0	9.86
<i>Risk factors</i>					
AADT	Average annual daily traffic (10^3 vehicles)	22.08	19.94	1.16	101.63
Width	Average width of each lane (m)	3.63	0.64	2.40	7.30
SL	Posted speed limit (km/h)	60.3	14.7	50	110
Merge	Number of merging ramps	0.84	1.00	0	4
Diverge	Number of diverging ramps	1.75	2.27	0	17
Inter	Number of intersections	1.90	2.37	0	16
Gradient	Average segment gradient (10^{-2})	0.04	2.74	-11	11
Curvature	Average segment curvature	21.9	17.5	0	85
LCO	Lane changing opportunity	2.43	1.61	0	7.85
Median	Presence of median barrier: yes = 1, no = 0	0.70	0.46	0	1
BS	Presence of bus stop: yes = 1, no = 0	0.64	0.48	0	1
Rainfall	Annual precipitation (m)	2.28	5.65	0.76	3.22

The lane changing opportunity (LCO) variable refers to the length-weighted average number of eligible opportunities to change lanes in a subsegment with identical lane markings. No lane changing is allowed in road sections with double continuous lines (as shown in Fig. 2(a)), thus $LCO=0$. In sections with one continuous line and one broken line, lane changing is only allowed from the side of

1 the broken line to the side of the continuous line (shown in Fig. 2(b)), thus $LCO=1$.
 2 In sections with a single broken line, lane changing is allowed between both adjacent
 3 lanes (as shown in Fig. 2(c)), thus $LCO=2$. Pei et al. (2012) provided a more
 4 detailed description of LCOs.



6 **Fig. 2.** Lane changing opportunities for different road section configurations.

8 4. Model estimation and result analysis

10 4.1. Model estimation

11 Without the requirement of the traditional maximum likelihood estimation for
 12 closed-form likelihood functions, Bayesian inference is able to handle very complex
 13 models (such as the random-parameters model in this study) (Lord and Mannering,
 14 2010). Moreover, Freeware WinBUGS, which is a popular platform for Bayesian
 15 inference, can be used to construct a flexible programming environment. As a
 16 consequence, both of the candidate models are programmed, estimated, and evaluated
 17 in WinBUGS, which is much more easily implemented than other alternatives, such as
 18 the maximum simulated likelihood estimation and copula methods (Anastasopoulos et
 19 al., 2012a, b).

21 In the absence of sufficient knowledge, non-informative priors are specified for
 22 the parameters and the hyper-parameters. Specifically, a diffused normal distribution

23 $N(0,10^4)$ is used as the priors of β_{km} and all of the elements of β_m

24 ($m = 0,1,\dots,12, k = 1,2$), and a Wishart prior $W(\mathbf{P}, r)$ is used for Σ^{-1} and Σ_m^{-1} ,

25 where $\mathbf{P} = \begin{bmatrix} 1, & 0 \\ 0, & 1 \end{bmatrix}$ represents the scale matrix and $r = 2$ is the degrees of freedom

26 (El-Basyouny and Sayed, 2009; Zeng et al., 2016). For each model, a chain of
 27 500,000 iterations of the Markov chain Monte Carlo (MCMC) simulation are made,
 28 with the first 4000 iterations acting as burn-ins. The Gelman-Rubin statistics available
 29 in WinBUGS is used to evaluate the MCMC convergence.

31 4.2. Model comparison

33 The results of DIC and a number of hyper-parameters for model comparison are

1 summarized in [Table 2](#). According to the results, it can be seen that the random effects
 2 of slight injury crash rates (σ_{11}) and KSI crash rates (σ_{22}), and their covariance
 3 $\sigma_{21} / \sigma_{12}$ in the multivariate random-parameters Tobit model, are all lower than their
 4 respective counterparts in the multivariate Tobit model, possibly because a portion of
 5 the random effects derived from the unobserved heterogeneity across observations is
 6 accounted for by the random parameters. In contrast to the random effects, the
 7 correlation coefficient $\rho (= \sigma_{12} / \sqrt{\sigma_{11}\sigma_{22}})$ is increased dramatically from 0.491 in the
 8 fixed-parameters model to 0.817 in the random-parameters model. It reveals that the
 9 crash rates at the two severity levels have a high positive correlation, which is
 10 reasonable as they are likely to rise due to the same deficiencies in roadway design
 11 and/or other unobserved factors ([El-Basyouny and Sayed, 2009](#)).

12
 13 **Table 2.** Model comparison results.

	Multivariate Tobit			Multivariate random-parameters Tobit		
	Mean	SD	95 % Credible interval	Mean	SD	95 % Credible interval
σ_{11}	3.442	0.154	(3.152, 3.753)^a	1.387	0.329	(0.809, 1.983)
$\sigma_{21}(=\sigma_{12})$	0.823	0.059	(0.712, 0.943)	0.465	0.081	(0.307, 0.617)
σ_{22}	0.816	0.036	(0.747, 0.890)	0.238	0.041	(0.165, 0.323)
ρ^b	0.491	0.024	(0.443, 0.538)	0.817	0.048	(0.711, 0.895)
R_1^2	0.305	0.005	(0.295, 0.314)	0.740	0.064	(0.616, 0.851)
R_2^2	0.158	0.006	(0.146, 0.168)	0.785	0.039	(0.703, 0.854)
R_T^2	0.356	0.003	(0.349, 0.360)	0.754	0.050	(0.659, 0.844)
$\overline{D(\theta)}$	6559			3440		
pD	29			1388		
DIC	6588			4828		

14 ^a Boldface indicates statistical significance at the 95 % credibility level.

15 ^b $\rho = \sigma_{12} / \sqrt{\sigma_{11}\sigma_{22}}$.

16

17 Moreover, the $\overline{D(\theta)}$ value of the multivariate random-parameters Tobit model
 18 (=3440) is much smaller than that of the multivariate Tobit model (=6559), which
 19 suggests that the random-parameters model fits the crash-rate data much better than
 20 the fixed-parameters model. It can be further confirmed by the Bayesian R^2 measure
 21 results that the values of R_1^2 , R_2^2 and R_T^2 of the multivariate random-parameters
 22 Tobit model are all greater than those of the multivariate Tobit model. These results
 23 are consistent with those in the previous research which shows that accommodating
 24 unobserved heterogeneity could significantly improve model fit ([Anastasopoulos and](#)

1 [Mannering, 2009; Anastasopoulos et al., 2012a](#)). Although there are more effective
 2 parameters (as reflected by pD) in the multivariate random-parameters Tobit model,
 3 which increase the complexity, its much lower DIC indicates that it substantially
 4 outperforms the multivariate Tobit model.

6 4.3 Interpretation of parameter estimation

8 The parameter estimation results in the multivariate Tobit and multivariate
 9 random-parameters Tobit models are presented in [Tables 3 and 4](#), respectively. From
 10 the results in [Table 4](#), we can see that the random-parameters' standard deviations of
 11 three factors (bus stop, lane changing opportunity and lane width)¹ are significant at
 12 the 95 % credibility level for both slight injury and KSI crash rates. They demonstrate
 13 the heterogeneous effects of these risk factors on the slight injury and KSI crash rates.

15 **Table 3.** Parameter estimation in the multivariate Tobit model^a.

Variable	Slight injury			KSI		
	Mean	SD	95% Credible interval	Mean	SD	95% Credible interval
Constant	3.656	0.574	(2.657, 4.725)^b	0.397	0.284	(-0.121, 0.920)
AADT	-0.024	0.004	(-0.033, -0.015)	-0.010	0.002	(-0.017, -0.003)
SL	-0.042	0.005	(-0.053, -0.030)	-0.009	0.003	(-0.016, -0.002)
Merge	-0.234	0.069	(-0.370, -0.100)	-0.093	0.033	(-0.158, -0.027)
Diverge	0.034	0.035	(-0.035, 0.104)	0.070	0.017	(0.036, 0.104)
Inter	-0.076	0.034	(-0.149, -0.002)	-0.086	0.019	(-0.122, -0.050)
Median	-0.438	0.182	(-0.787, -0.080)	-0.160	0.090	(-0.333, 0.017)
BS	0.601	0.150	(0.306, 0.895)	0.327	0.072	(0.186, 0.469)
Gradient	-3.072	2.125	(-7.266, 1.104)	-2.136	1.036	(-4.162, -0.114)
Curvature	-0.018	0.004	(-0.027, -0.009)	-0.004	0.002	(-0.011, 0.002)
LCO	0.254	0.045	(0.165, 0.342)	0.052	0.022	(0.009, 0.095)
Width	0.256	0.097	(0.072, 0.444)	0.197	0.048	(0.108, 0.289)

16 ^a Rainfall is excluded, because neither of its effects on crash rates at the two severity degrees is
 17 significant at the 95 % credibility level.

18 ^b Boldface indicates statistical significance at the 95 % credibility level.

20 Specifically, the presence of a bus stop results in normally distributed parameters,
 21 with means of 0.616 and 0.300 and standard deviations of 0.963 and 0.747 for slight
 22 injury and KSI crash rates, respectively. That is, the presence of a bus stop on most
 23 road segments (73.9 % and 65.6 %) increases the slight injury and KSI crash rates,
 24 probably because of the increased interaction between buses and other vehicles when
 25 they enter or leave bus bays ([Pei et al., 2012; Zeng et al., 2016](#)); however, for the
 26 minority of road segments (26.1 % and 34.4 %), the presence of a bus stop actually

¹ The covariance of the three pair of random parameters is not significant at the 95 % credibility level. Therefore, they are independently and normally distributed in the multivariate random-parameters Tobit model.

1 decreases the slight injury and KSI crash rates.

2 The effects of LCOs on the slight injury and KSI crash rates are found to follow
3 two independent normal distributions, with means of 0.235 and 0.052 and standard
4 deviations of 0.167 and 0.058, such that more LCOs would lead to a higher slight
5 injury (KSI) crash rate for 92 % (81.4 %) of roadway segments but a lower slight
6 injury (KSI) crash rate for the other 8 % (18.6 %). The general finding of LCOs (i.e.,
7 increasing slight injury and KSI crash rates) could be the result of increased vehicle
8 interaction caused by lane changing maneuvers (such as overtaking), which may
9 increase the incidence of traffic conflicts (Pei et al., 2012; Zeng et al., 2016).

10

11 **Table 4.** Parameter estimation in the multivariate random-parameters Tobit model^a.

Variable	Slight injury			KSI		
	Mean	SD	95 % Credible interval	Mean	SD	95 % Credible interval
Constant	3.508	0.429	(2.945, 4.238)^b	0.752	0.209	(0.401, 1.131)
AADT	-0.023	0.004	(-0.033, -0.014)	-0.008	0.002	(-0.015, -0.002)
SL	-0.040	0.005	(-0.051, -0.029)	-0.008	0.002	(-0.014, -0.001)
Merge	-0.205	0.065	(-0.331, -0.077)	-0.057	0.028	(-0.113, -0.001)
Diverge	0.021	0.035	(-0.046, 0.090)	0.049	0.016	(0.016, 0.081)
Inter	-0.073	0.037	(-0.141, -0.001)	-0.069	0.017	(-0.104, -0.035)
Median	-0.457	0.173	(-0.794, -0.147)	-0.194	0.080	(-0.350, -0.048)
BS	0.616	0.141	(0.341, 0.879)	0.300	0.063	(0.178, 0.423)
SD of BS	0.963	0.233	(0.515, 1.320)	0.747	0.055	(0.645, 0.852)
Curvature	-0.018	0.004	(-0.026, -0.009)	-0.004	0.002	(-0.010, 0.002)
LCO	0.235	0.045	(0.150, 0.318)	0.052	0.017	(0.020, 0.084)
SD of LCO	0.167	0.062	(0.070, 0.286)	0.058	0.018	(0.023, 0.090)
Width	0.320	0.097	(0.160, 0.486)	0.098	0.051	(0.009, 0.158)
SD of Width	0.256	0.039	(0.182, 0.321)	0.084	0.018	(0.046, 0.113)

12 ^a Gradient and Rainfall are excluded, because neither of their effects on crash rates at the two
13 severity degrees is significant at the 95 % credibility level.

14 ^b Boldface indicates statistical significance at the 95 % credibility level.

15

16 The mean and standard deviation of the random parameter of lane width for the
17 slight injury crash rates are 0.320 and 0.256, respectively, whereas those for the KSI
18 crash rates are 0.098 and 0.084, respectively. Given these distributional parameters
19 with their 95 % credible intervals away from zero, widening the lanes in 89.4 % and
20 87.8 % of roadway segments would increase the slight injury and KSI crash rates,
21 respectively, whereas widening the lanes of the remaining 10.6 % and 12.2 % would
22 have the opposite effect. Gross and Jovanis (2007) found a U-shaped relationship
23 between lane width and crash risk and speculated that drivers may respond to narrow
24 lanes with more-cautious behavior, thereby decreasing the likelihood of a crash.

25 With respect to the coefficients of the other factors, the positive or negative signs
26 are consistent and the magnitude is comparable in the two multivariate models.

1 Furthermore, the signs of each factor's coefficients for both slight injury and KSI
2 crash rates are identical, which means that they have consistent effects on the crash
3 rates for the two injury severity degrees. Nevertheless, the fixed parameters of
4 Constant and Median are changed to be significant but the effect of Gradient on the
5 KSI crash rates is changed to be insignificant at the 95 % credibility level in the
6 multivariate random-parameters Tobit regression. In addition, the standard deviations
7 of most coefficients are smaller in the random-parameters model, which indicates that
8 it leads to more precise parameter estimation.

9 Specifically, the average annual daily traffic is found to have significant negative
10 effects on both slight injury and KSI crash rates, which is consistent with the findings
11 in many previous studies (Anastasopoulos et al., 2012a, b; Huang et al., 2016b; Qi et
12 al., 2007). These findings may be attributed to the reduced travel speed caused by
13 increasing traffic volume, which may significantly decrease the likelihood of (slight
14 injury and SKI) crash occurrence. It is interesting to find that crash rates at the two
15 injury severity levels are both lower on roadway segments with higher speed limits,
16 which may contradict engineering intuition (Aguero-Valverde and Jovanis, 2008).
17 However, some researchers have argued that road segments designed for higher
18 speeds are usually well-planned, constructed, and managed (Milton and Mannering,
19 1998; Zeng et al., 2016) and that these features may improve highway safety
20 performance.

21 The significantly negative coefficients of Merge and Inter indicate that a greater
22 number of merging ramps and intersections on roadway segments are associated with
23 lower slight injury and KSI crash rates. These results could be explained by the risk
24 compensation theory, which suggests that drivers may adapt to an adverse driving
25 environment (more merging ramps and intersections) by altering their driving
26 behavior (such as being more careful or slowing down) (Mannering and Bhat, 2014).
27 Some drivers may overcompensate for the adverse conditions, leading to a lower
28 crash risk. Conversely, the positive coefficients of Diverge suggest that an increase in
29 the number of diverging ramps results in higher slight injury and KSI crash rates,
30 which conforms to engineering intuition and the findings of previous studies (Zeng et
31 al., 2016), because the sites that approach diverging ramps can be hazardous.

32 The estimation results show that the presence of a median barrier on a road
33 segment results in significantly lower slight injury and KSI crash rates. Studies have
34 suggested that median barriers can effectively prevent cross-median crashes (Donnell
35 and Mason, 2006; Zeng et al., 2016). Curvature is found to significantly decrease
36 slight injury crash rates, which may be somewhat counterintuitive. However, stronger
37 centrifugal force derived from greater road curvature tend to increase the injury
38 severity once a crash happens, that is, it is less likely to be a slight injury crash. This
39 may partially explain the significantly negative coefficient of Curvature on slight
40 injury crash rates.

41 42 **5. Conclusions and future research**

1
2 This study advocates a multivariate random-parameters Tobit model for the
3 simultaneous analysis of crash-injury-severity rates, which accommodates both
4 correlation between crash rates at different severity levels and unobserved
5 heterogeneity across observations. A crash dataset obtained from the Traffic
6 Information System maintained by the Transport Department of Hong Kong, in which
7 crashes are classified into slight injury and KSI degrees, is used to demonstrate the
8 proposed model and to compare it with a multivariate fixed-parameters Tobit model.
9 The models are estimated and evaluated in the Bayesian context via programming in
10 the freeware WinBUGS.

11 The results show that bus stop, lane changing opportunity and lane width present
12 heterogeneous effects on both slight injury and KSI crash rates. After accounting for
13 the heterogeneity of these factors' effects, the random effects and covariance are all
14 decreased to certain degrees while the correlation coefficient reaches 0.817, which
15 suggests a high positive correlation between the crash rates at the two severity levels.
16 The multivariate random-parameters Tobit model fits the collected crash data much
17 better than the multivariate Tobit model, as reflected by a dramatic decrease in the
18 DIC value (1760) and significant increases in the Bayesian R^2 values. What's more,
19 compared with the fixed-parameters model, the random-parameters model produces
20 consistent signs and more precise estimates for the fixed coefficients of the other
21 factors. The average annual daily traffic, the speed limit, the number of merging
22 ramps and intersections, and the presence of median barriers are found to have
23 significant negative effects on slight injury and KSI crash rates, while the number of
24 diverging ramps is found to have a significant positive association with KSI crash
25 rates.

26 In summary, the empirical analysis demonstrates the superiority of the
27 multivariate random-parameters Tobit model and the significance of correlation
28 between crash rates at various severity degrees and the heterogeneous effects of
29 certain risk factors in the crash-injury-severity-rate data. Noticeably, like other
30 random-parameters models, the proposed multivariate random-parameters Tobit
31 model may suffer from transferability issues since the individual parameter vector
32 associated with each observation is unique. However, if significant random
33 parameters are found in crash data, the fixed-parameters model will be estimated with
34 a persistent bias and transferability will be problematic since this bias will be a
35 function of unobserved heterogeneity (Mannering et al., 2016). Thus, we still think
36 that the proposed model has considerable potential in analysis of crash rates by
37 severity. Because significant spatial correlation always exists among crash rates of
38 adjacent road sites, further research effort could be devoted to incorporate spatial
39 correlation into the multivariate random-parameters Tobit model. It could also be
40 applied to rank sites that hold promise for safety improvement.

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