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<td><strong>Author(s)</strong></td>
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<tr>
<td><strong>Citation</strong></td>
<td>IEEE Transactions on Industrial Electronics, 2012, v. 59 n. 4, p. 1751-1759</td>
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<tr>
<td><strong>Issued Date</strong></td>
<td>2012</td>
</tr>
<tr>
<td><strong>URL</strong></td>
<td><a href="http://hdl.handle.net/10722/155689">http://hdl.handle.net/10722/155689</a></td>
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Dynamic Photoelectrothermal Theory for Light-Emitting Diode Systems

Xuehui Tao and S. Y. Ron Hui, Fellow, IEEE

Abstract—This paper presents a dynamic photoelectrothermal theory for light-emitting diode (LED) systems. In addition to photometric, electrical, and thermal aspects, this theory incorporates the time domain into the generalized equations. A dynamic model for a general LED system is developed for system analysis. This theory highlights the fact that the luminous output of an LED system will decrease with time from the initial operation to the steady state due to the rising temperature of the heat sink and the LED devices. The essential thermal time constants involved in the LED systems are explained. The time factor is critical in understanding how much the luminous output will decrease with time and is essential to the optimal designs of the LED systems that are operated continuously (e.g., general lighting) or momentarily (e.g., traffic lights). Experiments on several LED systems at different time frames have been conducted, and the practical measurements confirm the validity of this theory.

Index Terms—Light-emitting diodes (LEDs), lighting systems.

I. INTRODUCTION

In a recent Institution of Engineering and Technology article on lighting [1], comments are quoted about light-emitting diode (LED) products that “the majority of LED A-type replacement lamps do not meet manufacturer performance claims” and that “testing reveals that these lamps produce only 10% to 60% of their claimed light output.” Aside from the quality issues, one possible reason for such mismatch in the claimed and actual luminous performance is the misunderstanding of the luminous efficacy figures of the LED devices. LED device manufacturers usually cite high luminous efficacy figures which are only correct at a junction temperature under normal operation, it is not unusual that the luminous efficacy could drop by 25% or more [6].

Unlike traditional power electronic circuits, the main factor that needs to be optimized in a lighting system is the luminous efficacy [7], [20] instead of the energy efficiency [18]. Good luminous efficacy would automatically imply good efficiency, but not vice versa. The general (steady-state) photoelectrothermal (PET) theory for LED systems [7] has pointed out both theoretically and practically that an LED device will not necessarily generate the maximum amount of luminous output at its rated power unless the LED system is optimally designed in an integrated manner. Optimal design of LED systems can only be achieved with the proper choices of LED devices and array structure, LED driver, operating power, and thermal design. Various aspects of LED systems, such as the thermal management [8]–[11], nonlinear behavior of junction-to-case thermal resistance [12], LED drivers [13], [18], and current-sharing techniques for LED strings [14], [15], have been reported. While the interactions of photometric, electric, and thermal aspects of the LED systems have been linked together [7], [16], very limited research on the time dependence of the luminous performance of LED systems has been reported.

This time factor is in fact highly relevant to the actual luminous output of any LED system. For LED systems designed for continuous operation, such as road lighting systems and LED bulbs, the luminous output will drop from the initial operation to the steady state. The main reason is due to the gradual increase in the LED junction and heat-sink temperature values. Therefore, the time factor is critical in understanding how much luminous reduction an LED system will have so that proper LED systems can be designed. For LED systems with momentary or discontinuous operation, such as traffic lights and signal indicators of vehicles, the design criteria would be different from those for continuous operation. The PET theory [7] published in 2009 describes the steady-state performance of an LED system. As an extended version of [19], this paper incorporates the time domain into the PET theory so that the dynamic behavior of the LED systems can be studied in the time domain. This dynamic PET theory will converge to the steady-state theory under steady-state conditions. Since the luminous efficacy is the main design factor for LED systems, this dynamic theory provides a useful tool not only for studying the behavior of LED systems but also, more importantly, for optimizing LED system designs for both continuous and discontinuous operations.

II. DYNAMIC PET THEORY FOR LED SYSTEMS

A. Dynamic Equivalent Circuit for an LED System

Fig. 1 shows the thermal equivalent circuit of one LED mounted on a heat sink. The heat source \( P_{\text{heat}} \) is the amount of heat generated by the LED. The internal junction temperature of the LED device is \( T_J \). The thermal resistor and thermal
The amount of heat generated by an LED can be expressed as

\[ P_{\text{heat}} = k_h P_d \]  

where \( k_h \) is the heat dissipation coefficient that represents the portion of input power that is dissipated as heat [17] and \( P_d \) is the input power of each LED.

In Fig. 3, some heat \( (P_1) \) flows from the equivalent heat source through the equivalent thermal resistor, and another portion of the heat \( (P_{C_{jc}}) \) flows into the equivalent thermal capacitor of the LED package. Based on the thermal circuit analysis, it can be shown that

\[ P_{C_{jc}} = N k_h P_d - P_1 \]  

(2)

\[ P_{C_{jc}} = NC_{jc} \frac{d(T_j - T_a)}{dt} \]  

(3)

\[ P_1 = \frac{T_J - T_{hs}}{R_{jc}/N} \]  

(4)

Based on (2)–(4)

\[ NC_{jc} \frac{dT_j}{dt} = N k_h P_d - \frac{T_J - T_{hs}}{R_{jc}/N} \]  

(5)

Rearranging (5) gives

\[ \frac{dT_j}{dt} = \frac{1}{C_{jc} R_{jc}} T_j = \frac{k_h P_d}{C_{jc}} + \frac{T_{hs}}{C_{jc} R_{jc}} \]  

(6)

In practice, the thermal time constant of the LED package \( (\tau_{jc} = R_{jc} C_{jc}) \) is much smaller than that of the heat sink \( (\tau_{hs} = R_{hs} C_{hs}) \). The heat-sink temperature \( T_{hs} \) will change much slowly than the LED junction temperature \( T_j \). In order to avoid confusion, the terms “fast transient” and “slow transient” refer to the time frames in the order of the \( \tau_{jc} \) and \( \tau_{hs} \), respectively. Under a fast-transient situation, \( T_{hs} \) can be considered as a constant. Based on this argument, the dynamic relationship between \( T_j \) and \( T_{hs} \) under fast-transient condition can be obtained from (6) as

\[ T_j = R_{jc} k_h P_d \left( 1 - e^{-\frac{t}{\tau_{jc}}} \right) + T_{hs} \]  

(7)

For the heat sink, the heat flows into the thermal capacitor \( C_{hs} \) and the thermal resistor \( R_{hs} \) of the heat sink. The heat flow component \( P_1 \) can be expressed as

\[ P_1 = P_{C_{hs}} + P_2 \]  

(8)

where \( P_{C_{hs}} \) is the heat flowing into the thermal capacitor of the heat sink and \( P_2 \) is the heat through the thermal resistor of the heat sink. They can be formulated as

\[ P_{C_{hs}} = C_{hs} \frac{d(T_{hs} - T_a)}{dt} \]  

(9)

\[ P_2 = \frac{T_{hs} - T_a}{R_{hs}} \]  

(10)

From (4) and (8)–(10), the heat-sink temperature is therefore

\[ \frac{T_J - T_{hs}}{R_{jc}/N} = C_{hs} \frac{d(T_{hs} - T_a)}{dt} + \frac{T_{hs} - T_a}{R_{hs}} \]  

(11)

which can be rewritten as

\[ \frac{dT_{hs}}{dt} = \frac{N}{C_{hs} R_{jc}} T_j - \frac{NR_{hs} + R_{jc}}{C_{hs} R_{hs} R_{jc}} T_{hs} + \frac{T_a}{C_{hs} R_{hs}} \]  

(12)
Now, the relationship of $T_j$ and $T_{hs}$ obtained in (7) can be used in (12):

$$\frac{dT_{hs}}{dt} = \left[ \frac{N}{C_{hs} R_{jc}} \left( -R_{jc} k_h P_d e^{-\frac{T_{jc}}{T_{jc}}} + R_{jc} k_h P_d + T_{hs} \right) - \frac{N R_{hs} + R_{jc}}{C_{hs} R_{hs} R_{jc}} T_{hs} + \frac{T_a}{C_{hs} R_{hs}} \right].$$  \hspace{1cm} (13)

Solving (13), the heat-sink temperature $T_{hs}$ can be obtained as

$$T_{hs}(t) = \left[ -R_{jc} C_{jc} N R_{hs} k_h P_d - \frac{C_{jc} R_{jc} - C_{hs} R_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} e^{-\frac{\tau_{jc}}{T_{jc}}} \right] + N R_{hs} k_h P_d + A e^{-\frac{\tau_{hs}}{T_{hs}}} + T_a$$ \hspace{1cm} (14)

where $A$ represents a constant, which can be determined from the physical boundary condition of the heat sink. The boundary condition of a heat sink is that, at $t = 0$, the heat-sink temperature is equal to the ambient temperature. That is

$$T_{hs}(t = 0) = T_a.$$ \hspace{1cm} (15)

Putting (15) into (14), the coefficient $A$ can be obtained as

$$A = -\left( -R_{jc} C_{jc} N R_{hs} k_h P_d - \frac{C_{jc} R_{jc} - C_{hs} R_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} e^{-\frac{\tau_{jc}}{T_{jc}}} \right).$$

Putting $A$ into (14), the heat-sink temperature can be obtained as

$$T_{hs}(t) = \left[ -R_{jc} C_{jc} N R_{hs} k_h P_d - \frac{C_{jc} R_{jc} - C_{hs} R_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} e^{-\frac{\tau_{jc}}{T_{jc}}} \right] + N R_{hs} k_h P_d + \frac{N k_h P_d R_{hs}^2 C_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} e^{-\frac{\tau_{hs}}{T_{hs}}} + N R_{hs} k_h P_d + T_a.$$ \hspace{1cm} (16)

By putting the result of (16) into (7), the complete dynamic LED junction temperature $T_j$ is

$$T_j = \left[ -R_{jc} k_h P_d \left( \frac{C_{jc} N R_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} + 1 \right) e^{-\frac{\tau_{jc}}{T_{jc}}} + k_h P_d \frac{N R_{hs}^2 C_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} e^{-\frac{\tau_{hs}}{T_{hs}}} + (R_{jc} + N R_{hs}) k_h P_d + T_a \right].$$ \hspace{1cm} (17)

The luminous efficacy ($E$) has the following relationship with the junction temperature $T_j$ of the LED [7]:

$$E = E_o \left[ 1 + k_e (T_j - T_a) \right].$$ \hspace{1cm} (18)

Now, $T_j$ obtained in (17) can be used in (18):

$$E = E_o \left[ 1 + k_e (T_a - T_j) + k_e k_h (R_{jc} + N R_{hs}) P_d \right.$$

$$- k_e R_{jc} k_h P_d \left( \frac{N R_{hs} C_{jc}}{C_{jc} R_{jc} - C_{hs} R_{hs}} + 1 \right) e^{-\frac{\tau_{jc}}{T_{jc}}}$$

$$+ k_e k_h P_d \frac{N R_{hs}^2 C_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}} e^{-\frac{\tau_{hs}}{T_{hs}}} \right].$$ \hspace{1cm} (19)

Therefore, the total luminous flux $\phi_v$ is

$$\phi_v = N E_o \left[ 1 + k_e (T_a - T_o) + k_e k_h (R_{jc} + N R_{hs}) P_d \right.$$

$$- k_e R_{jc} k_h P_d \left( \frac{N R_{hs} C_{jc}}{C_{jc} R_{jc} - C_{hs} R_{hs}} + 1 \right) e^{-\frac{\tau_{jc}}{T_{jc}}}$$

$$\times e^{-\frac{\tau_{hs}}{T_{hs}}} P_d + k_e k_h \frac{N R_{hs}^2 C_{hs}}{C_{jc} R_{jc} - C_{hs} R_{hs}}$$

$$\times e^{-\frac{\tau_{hs}}{T_{hs}}} P_d \right].$$ \hspace{1cm} (20)

Equations (16)–(20) now form the set of dynamic equations that describe the essential variables of the LED system. These dynamic equations can converge to the steady-state equations as the time variable $t$ approaches infinity.

As $t \to \infty$, (16) becomes

$$T_{hs}(t) = N R_{hs} k_h P_d + T_a$$ \hspace{1cm} (21)

(17) becomes

$$T_j = (R_{jc} + N R_{hs}) k_h P_d + T_a$$ \hspace{1cm} (22)

(19) becomes

$$E = E_o \left[ 1 + k_e (T_a - T_o) + k_e k_h (R_{jc} + N R_{hs}) P_d \right]$$ \hspace{1cm} (23)

and (20) becomes

$$\phi_v = N E_o \left[ 1 + k_e (T_a - T_o) \right] P_d + k_e k_h (R_{jc} + N R_{hs}) P_d^2.$$ \hspace{1cm} (24)

It can be seen that (21)–(24) are identical to the steady-state equations of the general PET theory reported in [7]. In practice, the ventilation of a LED system is affected by the lighting fixture design. In this case, the heat-sink thermal resistance should be measured in the presence of the lighting fixture. By warming up the heat sink with a known resistor driven by a given power, the thermal time constant of the heat sink can be extracted [19].

### III. Experimental Verification

Three types of LED devices are used to evaluate the validity of the dynamic PET theory. Each type of LED device is mounted on two different heat sinks, and the luminous outputs and LED power levels are recorded at several intervals during the test periods. Luminous and power measurements are taken with the use of a spectrophotocolorimeter system that includes accessories such as integrating sphere and power supplies. The current of the LEDs is controlled by an adjustable power supply with constant current control. The heat sinks on which the LEDs are mounted are placed on one side of the internal surface of an integrating sphere for luminous measurements. Thermal couplers are mounted on the heat sinks in order to monitor the temperature rise of the heat sinks, and the temperature values are recorded with a data logger. Although it is not advisable to operate the LEDs beyond their rated power, the LEDs in
Table I

<table>
<thead>
<tr>
<th>$k_c$</th>
<th>$k_h$</th>
<th>$E_o$</th>
<th>$T_a$</th>
<th>$T_o$</th>
<th>$N$</th>
<th>$R_{hs}$</th>
<th>$R_{jc}$</th>
<th>$\tau_{LED}$</th>
<th>$\tau_{hs}$</th>
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<td>-0.0053</td>
<td>0.9</td>
<td>36</td>
<td>28</td>
<td>25</td>
<td>4</td>
<td>10</td>
<td>15</td>
<td>0.3</td>
<td>450</td>
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</table>

Fig. 4. Measured luminous flux for four Philips-Luxeon LEDs mounted on a heat sink with $R_{hs} = 10 \, ^\circ C/W$.

Fig. 5. Calculated luminous flux for four Philips-Luxeon LEDs mounted on a heat sink with $R_{hs} = 10 \, ^\circ C/W$.

These tests are powered beyond their rated values in order to provide more data for verifying the dynamic PET theory. The thermal time constants of the LED devices are obtained from the measurements using the T3ster system. Those of the heat sinks are estimated from the temperature reduction curves of the heat sinks (obtained by heating the heat sink to a certain temperature and then letting it cool down naturally). Other parameters are obtained from the manufacturers’ data sheets or from previous measurements.

A. Tests on Philips-Luxeon 1-W LEDs (Model Number: LXHL-PW01)

In each test, four Luxeon 1-W LEDs are mounted on the heat sink, and the luminous flux curves are recorded at different time intervals. The thermal resistances of the heat sink Sample A and Sample B are 10 $^\circ C/W$ and 7.1 $^\circ C/W$, respectively. Table I shows the measured data.

1) On a Heat Sink With Thermal Resistance of 10 $^\circ C/W$:

The curves of the luminous flux are measured and recorded at different time intervals as shown in Fig. 4. The parameters $\tau_{LED}$, $\tau_{hs}$, and $R_{hs}$ have already been measured and are listed in Table I. Based on the dynamic PET theory, the theoretical curves of the luminous flux obtained from (20) at the same time intervals are plotted in Fig. 5. These results are in agreement in general.

Table II

<table>
<thead>
<tr>
<th>$k_c$</th>
<th>$k_h$</th>
<th>$E_o$</th>
<th>$T_a$</th>
<th>$T_o$</th>
<th>$N$</th>
<th>$R_{hs}$</th>
<th>$R_{jc}$</th>
<th>$\tau_{LED}$</th>
<th>$\tau_{hs}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>-0.0053</td>
<td>0.9</td>
<td>36</td>
<td>28</td>
<td>25</td>
<td>4</td>
<td>7.1</td>
<td>15</td>
<td>0.3</td>
<td>500</td>
</tr>
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</table>

Fig. 6. Measured luminous flux for four Philips-Luxeon LEDs mounted on a heat sink with $R_{hs} = 7.1 \, ^\circ C/W$.

Fig. 7. Calculated luminous flux for four Philips-Luxeon LEDs mounted on a heat sink with $R_{hs} = 7.1 \, ^\circ C/W$.

B. Tests on CREE XLamp XR-E 3-W LEDs (Model Number: XREWHT-LI-WG-Q5-0-04)

Eight CREE 3-W LEDs are mounted on heat sinks in two sets of tests with the heat-sink thermal resistance equal to 2.9 $^\circ C/W$ (Sample C) and 1.8 $^\circ C/W$ (Sample D). Table III shows the measured data.

1) On a Heat Sink With Thermal Resistance of 2.9 $^\circ C/W$:

The measured luminous flux curves at different time intervals are shown in Fig. 6. Using the parameters shown in Table II, the theoretical curves are obtained and plotted in Fig. 7. The measured and theoretical results show good agreement.

Table III

<table>
<thead>
<tr>
<th>$k_c$</th>
<th>$k_h$</th>
<th>$E_o$</th>
<th>$T_a$</th>
<th>$T_o$</th>
<th>$N$</th>
<th>$R_{hs}$</th>
<th>$R_{jc}$</th>
<th>$\tau_{LED}$</th>
<th>$\tau_{hs}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>-0.0053</td>
<td>0.87</td>
<td>100</td>
<td>28</td>
<td>25</td>
<td>8</td>
<td>2.9</td>
<td>8</td>
<td>0.45</td>
<td>510</td>
</tr>
</tbody>
</table>

2) On a Heat Sink With Thermal Resistance of 7.1 $^\circ C/W$:

The measured luminous flux curves at different time intervals are shown in Fig. 6. Using the parameters shown in Table II, the theoretical curves are obtained and plotted in Fig. 7. The measured and theoretical results show good agreement.
plotted in Fig. 9. Very good agreements between the measured and theoretical curves are observed.

2) On a Heat Sink With Thermal Resistance of 1.8 °C/W:
The curves of the luminous flux are measured and recorded at different time intervals as shown in Fig. 10. The parameters $\tau_{LED}$, $\tau_{hs}$, and $R_{hs}$ have already been measured and are listed in Table IV. Based on the dynamic PET theory, the theoretical curves of the luminous flux obtained from (20) at the same time intervals are plotted in Fig. 11.

C. Tests on SHARP 3-W LEDs

Similar tests are repeated on eight SHARP 3-W LEDs mounted on heat sinks—Sample C and Sample D.

1) On a Heat Sink With Thermal Resistance of 2.9 °C/W:
The measured luminous flux curves at different time intervals are shown in Fig. 12. Table V shows the parameters used for the theoretical prediction, and the theoretical curves are shown in Fig. 13.

2) On a Heat Sink With Thermal Resistance of 1.8 °C/W:
The measured luminous flux at different time intervals is
Fig. 14. Measured luminous flux for eight SHARP 3-W LEDs mounted on a heat sink with $R_{hs} = 1.8^\circ$C/W.

### Table VI

**LED System Parameters**

<table>
<thead>
<tr>
<th>$k_e$</th>
<th>$k_h$</th>
<th>$E_0$</th>
<th>$T_a$</th>
<th>$T_e$</th>
<th>$N$</th>
<th>$R_{hs}$</th>
<th>$R_{jc}$</th>
<th>$\tau_{LED}$</th>
<th>$\tau_{hs}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>-0.0045</td>
<td>0.87</td>
<td>104</td>
<td>28</td>
<td>25</td>
<td>8</td>
<td>1.8</td>
<td>6.5</td>
<td>0.75</td>
<td>520</td>
</tr>
</tbody>
</table>

Fig. 15. Calculated luminous flux for eight SHARP 3-W LEDs mounted on a heat sink with $R_{hs} = 1.8^\circ$C/W.

Fig. 16. Variation of the luminous flux with time for four Luxeon 1-W LEDs operated at rated power.

Fig. 17. Variation of the luminous flux with time for eight CREE 3-W LEDs operated at rated power.

Fig. 18. Variation of the luminous flux with time for eight SHARP 3-W LEDs operated at rated power.

Recorded in Fig. 14. With the parameters listed in Table VI, the theoretical luminous flux curves are plotted in Fig. 15. These results agree well with the measurements.

**IV. REDUCTION OF LUMINOUS FLUX WITH TIME**

Based on the practical and theoretical results obtained in Section III, the variations of the luminous flux with time under the operations at rated power for the three types of LEDs are shown in Fig. 16 (Luxeon 1-W LEDs), Fig. 17 (CREE 3-W LEDs), and Fig. 18 (SHARP 3-W LEDs). When mounted on a heat sink with $R_{hs} = 2.9^\circ$C/W, both CREE 3-W LEDs and SHARP 3-W LEDs exhibit a luminous reduction of about 20%. However, when mounted on a heat sink with $R_{hs} = 1.8^\circ$C/W, they only have a luminous reduction of 10%. Similar results are obtained from the Luxeon 1-W LEDs, which have less luminous reduction when mounted on a larger heat sink with a smaller $R_{hs}$.

Several observations can therefore be made from these results, from which some insights into the design guidelines of LED systems can be derived.

1) Some differences between the measured and calculated curves are observed. Such differences might be due to the assumptions made in the theoretical calculations. The assumption that all LED devices are identical and share the same temperature and power is not exactly true in practice. In fact, there are variations among LEDs of the same type and even of the same bin. The efficacy reduction rate $k_e$ is also affected by the ageing of the LED devices. Nevertheless, the dynamic PET theory can predict the general trends of the luminous flux output as functions of time fairly accurately.

2) It is important for the LED system designers and product manufacturers to use the steady-state luminous flux and efficacy as rated values if the LED systems are used continuously. However, for applications in which the LED systems are turned on momentarily, a different time-dependent curve should be selected.

3) The amount of luminous flux reduction depends on the thermal design and is more serious in LED systems using heat sinks with high thermal resistance (as predicted...
in both steady-state and dynamic theories). In order to reduce the luminous reduction of an LED system, it is necessary to design a heat sink with good cooling effects.  

4) The results in Fig. 16–18 indicate that the luminous flux outputs of the same number of LEDs mounted on different heat sinks are initially close to each other because the temperature rise of the heat sinks is not significant initially. This implies that, for temporary applications such as traffic lights in which the amber light is turned on typically 5 s and the green light is turned on 25 to 120 s, a small heat sink is sufficient. Therefore, the luminous flux, as predicted by this dynamic theory, with a small time can be used as the designed luminous flux.  

5) However, for continuous operation such as road lighting, the luminous flux projected at the steady state should be used as the prediction. It is therefore necessary to ensure that the thermal design can meet the luminous requirements at steady-state operation.  

V. CONCLUSION  

A dynamic PET theory has been developed and practically verified. The main contribution of this paper is the introduction of the time domain and, thus, dynamics to the steady-state PET theory. This dynamic PET theory confirmed by practical measurements highlights the time dependence of the luminous flux of an LED system. The luminous flux of an LED system tends to decrease with time because of the gradual temperature rise in the heat sink and, therefore, the junction of the LED. This means that LED systems with continuous and discontinuous operation should be designed according to different time-dependent luminous flux curves. This theory opens a door to the accurate prediction of the luminous flux output for a given LED system design. Three types of LEDs have been modeled and practically tested with different heat sinks. The practical and theoretical results obtained for these LED systems are generally in good agreement, confirming the validity of the dynamic PET theory. This dynamic theory enables the study of the photometric, electric, thermal, and temporal aspects of an LED system in a systematic manner and provides a tool for the optimal design of LED systems.  

APPENDIX  

In the main text of this paper, the thermal time constant of the LED package is much smaller (typically a thousand times smaller in practice) than that of the heat sink. Equation (7) thus assumes that the heat-sink temperature \( T_{hs} \) remains constant during the fast transient. The thermal dynamics of the heat sink is handled separately. If this assumption is removed, a more rigorous analysis is presented here.  

In Fig. 1, the heat will flow from the equivalent heat source through the thermal resistor \( (P_1) \), and another portion of the heat will flow into the thermal capacitor \( (P_{Cj}) \) of the LED package. Based on thermal circuit analysis, it can be shown that  

\[
P_{Cj} = Nk_hP_d - P_1 \quad \text{(A1)}
\]

\[
P_{Cj} = NC_{jc} \frac{d(T_j - T_a)}{dt} \quad \text{(A2)}
\]

\[
P_1 = \frac{T_j - T_{hs}}{R_{jc}/N} \quad \text{(A3)}
\]

Based on (A1)–(A3), we have the relationships  

\[
NC_{jc} \frac{d(T_j - T_a)}{dt} = Nk_hP_d - \frac{T_j - T_{hs}}{R_{jc}/N} \quad \text{(A4)}
\]

\[
T_{hs} = R_{jc}C_{jc} \frac{dT_j}{dt} + T_j - R_{jc}k_hP_d \quad \text{(A5)}
\]

\[
\frac{dT_{hs}}{dt} = R_{jc} \frac{dT_j}{dt}^2 + \frac{dT_j}{dt} \quad \text{(A6)}
\]

for the heat sink.  

The items \( T_{hs} \) and \( dT_{hs}/dt \) expressed in (A5) and (A6) can be used in (12). Now, putting (A5) and (A6) into (12), the differential equation of \( T_j \) can be obtained as  

\[
R_{jc}C_{jc}R_{hs}C_{hs} \frac{dT_j}{dt^2} + (R_{jc}C_{jc}+R_{hs}C_{hs}+NR_{hs}C_{jc}) \frac{dT_j}{dt} + T_j = (R_{jc} + NR_{hs})k_hP_d + T_a. \quad \text{(A7)}
\]

Solving (A7), the expression of \( T_j \) can be obtained  

\[
T_j = A_1e^{\lambda_1t} + A_2e^{\lambda_2t} + (R_{jc} + NR_{hs})k_hP_d + T_a. \quad \text{(A8)}
\]

By bringing (A8) into (A5), the heat-sink temperature can be obtained  

\[
T_{hs} = R_{jc}C_{jc}A_1e^{\lambda_1t} + R_{jc}C_{jc}A_2e^{\lambda_2t} + A_1e^{\lambda_1t} + A_2e^{\lambda_2t} + NR_{hs}k_hP_d + T_a. \quad \text{(A9)}
\]

\( A_1 \) and \( A_2 \) are coefficients which can be determined using the physical boundary condition.  

The boundary condition is that, at \( t = 0 \), the heat-sink temperature and the LED temperature are equal to the ambient temperature  

\[
T_{hs}(t = 0) = T_a \\
T_j(t = 0) = T_a. \quad \text{(A10)}
\]

Using (A10) into (A8) and (A9), the constants \( A_1 \) and \( A_2 \) can be obtained.  

Therefore, according to (18), the total luminous flux \( \phi_v \) is  

\[
\phi_v = NEP_d \\
= NE_o[1 + k_e(T_a - T_o)]P_d \\
+ NE_o k_e k_h (R_{jc} + NR_{hs}) P_d^2 + NE_o k_e (A_1e^{\lambda_1t} + A_2e^{\lambda_2t}) P_d \quad \text{(A11)}
\]
Fig. 19. Calculated luminous flux for eight CREE XLamp XR-E LEDs mounted on a heat sink with $R_{th,s} = 1.8 \, {\mathsf{^oC/W}}$ by the vigorous analysis.

where

$$\lambda_1 = \frac{\sqrt{(R_{jc}C_{jc} + R_{hs}C_{hs} + NR_{hs}C_{jc})^2 - 4R_{jc}C_{jc}R_{hs}C_{hs}}}{2R_{jc}C_{jc}R_{hs}C_{hs}}$$

$$\lambda_2 = -\frac{R_{jc}C_{jc} + R_{hs}C_{hs} + NR_{hs}C_{jc}}{2R_{jc}C_{jc}R_{hs}C_{hs}}$$

$$A_1 = \frac{k_hP_d + \lambda_1 C_{jc}(R_{jc} + NR_{hs})k_hP_d}{C_{jc}(\lambda_1 - \lambda_2)}$$

$$A_2 = \frac{k_hP_d + \lambda_1 C_{jc}(R_{jc} + NR_{hs})k_hP_d}{C_{jc}(\lambda_2 - 1)}$$

Based on this vigorous analysis, the theoretical luminous flux curves for the test with eight CREE LEDs mounted on a heat sink with $R_{th,s} = 1.8 \, {\mathsf{^oC/W}}$ are plotted in Fig. 19. The results from this vigorous analysis are very close to the practical measurements in Fig. 10 and the theoretical results using the simplified analysis in Fig. 11.

ACKNOWLEDGMENT

The authors would like to thank B. Ngan for his assistance in obtaining the luminous measurements. The authors would also like to thank the Centre for Power Electronics, City University of Hong Kong, for its support for the project.

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