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An efficient algorithm for optimizing whole genome alignment with noise

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ABSTRACT

Motivation: This paper is concerned with algorithms for aligning two whole genomes so as to identify regions that possibly contain conserved genes. Motivated by existing heuristic-based software tools, we initiate the study of an optimization problem that attempts to uncover conserved genes with a global concern. Another interesting feature in our formulation is the tolerance of noise, which also complicates the optimization problem. A brute-force approach takes time exponential in the noise level.

Results: We show how an insight into the optimization structure can lead to a drastic improvement in the time and space requirement [precisely, to $O(k^2 n^2)$ and $O(k^2 n)$, respectively, where $n$ is the size of the input and $k$ is the noise level]. The reduced space requirement allows us to implement the new algorithm, called MaxMinCluster, on a PC. It is exciting to see that when tested with different real data sets, MaxMinCluster consistently uncovers a high percentage of conserved genes that have been published by GenBank. Its performance is indeed favorably compared to MUMmer (perhaps the most popular software tool for uncovering conserved genes in a whole-genome scale).

Availability: The source code is available from the website http://www.csis.hku.hk/~colly/maxmincluster/. Detailed proof of the propositions can also be found there.

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INTRODUCTION

This paper is concerned with algorithms for aligning the whole genomes of two related species so as to identify regions on the genomes that possibly contain their conserved genes. This problem has attracted a lot of attention in the last few years and a number of software tools have been developed (Bai11ie and Rose, 2000; Buhler, 2001; Delcher et al., 1999, 2002; Kurtz et al., 2004; Morgenstern, 1999; Morgenstern et al., 1998; Schwartz et al., 2000; Vincens et al., 1998). Whole genome alignment has also been studied for other applications (Altschul et al., 1997; Batzoglou et al., 2000; Frazer et al., 2003; Nieduszynski et al., 2002).

Related species (such as mouse and human) often have a lot of genes conserved, i.e. having the same functionality. Though a conserved gene rarely comprises the same entire sequence in two genomes [probably due to mutations (Gangloff et al., 1996; Mushegian and Koonin, 1996; Plasterk, 1993; Griffiths et al., 2000)], there are usually a lot of short common substrings and some of these substrings are indeed unique to this conserved gene. Thus, the first step to align two genomes would be to identify pairs of maximal substrings that appear uniquely in both genomes. This can be done in linear time using suffix trees (Gusfield, 1997). Of course, not every pair of matched substrings correspond to a conserved gene; in fact, most matched substrings in the input are “noise” and many of them actually originate from intergenic regions. Extracting the right pairs is not a trivial problem. See Figure 1 for an example.

Matched substrings that are noise are usually short and isolated. A conserved gene usually corresponds to a sequence of matched substrings that are consecutive and close in both genomes and have sufficient length. We call such a sequence a cluster. A collection of clusters gives us an alignment of the conserved genes between the two given genomes. At first glance, the problem of finding conserved genes is a simple clustering problem. Such a clustering approach has been used in practice (Delcher et al., 2002), yet the success is limited. There are two major concerns.

- Some conserved genes do not induce clusters of sufficient size; the primary reason is the presence of noise (which separates the actual matched substrings). To uncover such genes, we have to relax the definition of a cluster to allow the presence of noise.
- To report an alignment, one can simply use some ad hoc or greedy approach to cluster the pairs, but this does not have much control over the quality of the alignment. It is more desirable to find an alignment that satisfies some instinctive criterion, say, maximizing the size of the smallest cluster. Such a criterion could possibly improve the overall quality of the alignment as we avoid reporting relatively small clusters, which are less likely to be conserved genes. But imposing such a criterion increases...
It requires only \( \Theta(k^2 \cdot n^2) \) time, where \( n \) is the number of matched substrings in the input. In this paper we show how to exploit the structure of the problems to devise a more efficient algorithm; it requires only \( O(k^2) \) time for a pair of regions on average, and \( O(k^2 n^2) \) time for checking all pairs. This improvement allows us to solve the optimization problem in \( O(k^2 n^2) \) time using dynamic programming.

A straightforward implementation of the dynamic programming would require \( O(k n^2) \) space. This is actually too demanding. For example, in a pair of human and mouse chromosomes, there can be up to a hundred thousand pairs of matched substrings. Assuming \( k = 3 \), we already need \( > 10 \) GB of memory to implement this algorithm, which far exceeds the capacity of ordinary workstations. Fortunately, we are able to reduce the space requirement of the algorithm to \( O(k^2 n) \), while maintaining the same time complexity.

The new algorithm, which will be referred to as MaxMinCluster, has been implemented on a PC and compared with a heuristic-based software tool called MUMmer-3 (Kurtz et al., 2004) (which is currently the most popular whole genome alignment software tool). The evaluation of DNA sequence alignment was based on ten pairs of human and mouse chromosomes. Furthermore, we have tested both software tools for aligning translated protein sequences; notice that detecting protein sequence homology is particularly needed for distantly related genomes. For this purpose, we evaluated the software tools using nine virus genomes.

It is encouraging to see that for aligning DNA sequences, MaxMinCluster consistently achieves better coverage while preserving the sensitivity (for coverage, we count the percentage of published conserved genes that are reported; for sensitivity, we count the percentage of the reported clusters that are known to reside in a conserved gene; note that sensitivity is only an estimate as the literature has not yet identified all conserved genes). In some cases, the coverage of MaxMinCluster is as high as 1.5 times of MUMmer-3. See the section on experimental results for details. For aligning translated protein sequences, both software tools are able to achieve very high coverage (an average of 92%) when aligning the human and mouse chromosomes, MaxMinCluster has a slightly better sensitivity, though. For the case of virus, MaxMinCluster shows a higher coverage consistently.

Remarks We have also studied another optimization problem which is to find an alignment that minimizes the number of clusters. This selection criterion does not favor small clusters either. We have derived a dynamic programming algorithm whose performance is very similar to MaxMinCluster in terms of coverage, and space and time complexity (see our website).

**AN OPTIMIZATION PROBLEM**

The input is a sequence \( M = (m_1, m_2, \ldots, m_n) \), where each \( m_i \) denotes a pair of uniquely matched substrings on two given genomes \( A \) and \( B \). More precisely, each \( m_i \) is represented as a 4-tuple \( (a_i, b_i, \ell_i, \sigma_i) \) where \( a_i \) and \( b_i \) are respectively the starting positions on \( A \) and \( B \), \( \ell_i \) the length of the substrings and \( \sigma_i \) the orientation of the substrings. A pair of matched substrings on two genomes can originate from two sense strands of the same orientation or from a sense strand and an antisense strand of opposite orientations. If \( m_i \) is of same orientation, we set \( \sigma_i = 1 \); if \( m_i \) is of opposite orientations, we set \( \sigma_i = -1 \). Intuitively, same orientation means that the \( a_i \)-th character of...
the sense strand of \( A \) matches the \( b_i \)-th character of the sense strand of \( B \), the \((a_i + 1)\)-th matches the \((b_i + 1)\)-th and so on; while opposite orientations mean that the \( a_i \)-th character of the sense strand of \( A \) matches the \((b_i + \ell_i - 1)\)-th character of the antisense strand of \( B \), the \((a_i + 1)\)-th matches the \((b_i + \ell_i - 2)\)-th and so on. We assume that \( a_1 < a_2 < \cdots < a_n \). Let MinSize and Gap be two predefined positive constants.

**Noisy clusters**

A segment of \( M \) is a subsequence in the form \((m_j, m_{j+1}, \ldots, m_{j+k})\). Let \( k \) be a positive integer. We say that a segment of \( M \) is a \( k \)-noisy cluster if we can remove at most \( k \) elements from the segment, denoted by \( X \), such that the resulting subsequence \( S \) satisfies the following conditions:

1. The \( s_\ell \)s of all \( m_j \)s in \( S \) are the same.
2. If \( s_\ell = 1 \), both the \( a_\ell \)s and \( b_\ell \)s of \( S \) are increasing; otherwise, the \( a_\ell \)s are increasing while the \( b_\ell \)s are decreasing.
3. For any two consecutive elements \( m_p \) and \( m_q \) in \( S \), we require that they satisfy some kind of distance requirement. Let \( g_1 = |a_p - a_q| \) and \( g_2 = |b_p - b_q| \). A simple distance requirement is \( g_1 \leq \text{Gap} \) and \( g_2 \leq \text{Gap} \).
4. \( \text{Size}(S) \), defined to be \( \sum_{m_j \in S} \ell_j \), is at least MinSize. This is called the size requirement.

Intuitively, \( X \) corresponds to the noise.

**Alignment**

An alignment of \( M \), denoted \( A \), is a maximal collection of disjoint \( k \)-noisy clusters, i.e.

- clusters in \( A \) are mutually disjoint;
- there does not exist another \( k \)-noisy cluster which is disjoint with all clusters in \( A \) (i.e. we cannot add more clusters to \( A \));
- there does not exist another \( k \)-noisy cluster which includes some cluster(s) in \( A \) and is disjoint with all other clusters in \( A \) (i.e. we cannot enlarge any cluster in \( A \)).

**Max–min alignment problem**

We define the weight of a \( k \)-noisy cluster \( C \) as follows. Note that there may be more than one subset \( X \) that makes \( C \) qualified as a \( k \)-noisy cluster. Among all such \( X \)s, let \( X_o \) be the one with the smallest size. Define \( w(C) \), the weight of \( C \), to be \( \text{Size}(C - X_o) \).

The max–min alignment problem is defined as follows. Given a set \( M \) of pairs of matched substrings, we want to find an alignment \( A^* \) of \( M \) such that

\[
\min_{C \in A^*} w(C) = \max_{A \in \Sigma} \min_{C \in A} w(C),
\]

where \( \Sigma \) denotes the set of all possible alignments of \( M \). We call \( A^* \) an optimal alignment of \( M \) and \( \min_{C \in A^*} w(C) \) the weight of \( A^* \).

**ALGORITHM AND IMPLEMENTATION**

The dynamic programming algorithm

In this section, we describe a dynamic programming algorithm, called MaxMinCluster, for the max–min alignment problem. Recall that the input is a sequence \( M = (m_1, m_2, \ldots, m_n) \) and \( \Sigma \) denotes the set of all alignments of \( M \). We want to find an optimal alignment \( A^* \) of \( M \), i.e. \( \min_{C \in A^*} w(C) = \max_{A \in \Sigma} \min_{C \in A} w(C) \). Intuitively, this selection criterion does not favor small clusters, which are less likely to be conserved genes. The dynamic programming algorithm computes \( A^* \) incrementally, by considering the sequences \((m_1), (m_1, m_2), \ldots, (m_1, m_2, \ldots, m_j)\) and so on. Roughly speaking, for any \( 1 \leq j \leq n \), the algorithm finds the optimal alignment involving \((m_1, m_2, \ldots, m_j)\) by considering every \( k \)-noisy cluster \((m_i, m_j)\) for some \( 1 \leq i \leq j \) and the alignment involving \((m_1, m_2, \ldots, m_i)\); the best alignment is chosen by trying all such \( j \) values. Details are as follows.

For \( 1 \leq j \leq n \), let \( \Phi_j \) be the set of all possible \( k \)-noisy clusters of \( M \) whose elements are in \((m_1, m_2, \ldots, m_j)\). Let \( \Sigma_j \) be the set of all maximal collections of disjoint \( k \)-noisy clusters in \( \Phi_j \). Define

\[
w(j) = \max_{A \in \Sigma_j} \min_{C \in A} w(C).
\]

Note that \( \Phi_n \) equals the set of all possible \( k \)-noisy clusters of \( M \) and \( \Sigma_n = \Sigma \). Thus, \( w(n) \) is the weight of the optimal alignment of \( M \). To find \( w(j) \), we consider two cases according to whether \( m_j \) is included in some cluster in the alignment. Let \( \Gamma_j \subseteq \Sigma_j \) be the set of those maximal collections each of which has a \( k \)-noisy cluster containing \( m_j \). We define

\[
\overline{w}(j) = \max_{A \in \Gamma_j} \left( \min_{C \in A} w(C) \right),
\]

and

\[
\overline{e}(j) = \max_{A \in \Sigma_j - \Gamma_j} \left( \min_{C \in A} w(C) \right).
\]

Obviously, \( w(j) = \max[w(j), \overline{w}(j)] \).

The computation of \( \overline{w}(j) \) and \( \overline{e}(j) \) requires us to determine whether a segment of \( M \) in the form \((m_i, m_{i+1}, \ldots, m_j)\) is a \( k \)-noisy cluster, for all \( 1 \leq i \leq j \). To ease our discussion, we denote the segment \((m_i, m_{i+1}, \ldots, m_j)\) as \( M_{ij} \). Proposition 1 states that the computation can be done recursively. We first give the intuitive ideas.

Let \( S_j \) be the set of the starting positions of all segments which end at position \( j \) and which form a \( k \)-noisy cluster. For

\[\text{Another useful form of distance requirement is } |g_1 - g_2| \leq \text{Diff},\text{ and }|g_1 - g_2| \leq \text{Ratio} \cdot \max\{|g_1|, |g_2|\},\text{ where Diff and Ratio are predefined constants. As to be shown, our algorithm is applicable for any distance requirement.} \]
every \( i \in S_j \), the best alignment in \( \Sigma_j \) that contains \( M_{ij} \) is the union of \( \{M_{ij}\} \) and the best alignment in \( \Sigma_{i-1} \). On the other hand, let \( i^* \) be the largest position in \( S_j \). Let \( h \) be the largest index of the matched substring pair in some alignment \( A \in \Sigma_j - T_j \). Note that \( i^* \leq h \leq j - 1 \), otherwise, \( A \cup \{M_{ij}\} \) is an alignment which contradicts that \( A \) is maximal. Therefore, we can compute \( W(i, j) \) and \( WE(j) \) recursively as follows.

**Proposition 1.** Assume that \( \bar{w}(0) = \bar{w}(0) = \bar{w}(0) = 0 \). Then, for any \( j \geq 1 \),

\[
W(j) = \max \left\{ \max_{i \in S_j, \bar{w}(i-1) = 0} \min (\bar{w}(i-1, w(M_{ij}))), \max_{i \in S_j, \bar{w}(i-1) = 0} w(M_{ij}) \right\};
\]
\[
WE(j) = \begin{cases} 
\max_{h \in \{i^*+1, \ldots, j-1\}} \bar{w}(h) & \text{if } S_j \neq \emptyset, \\
\bar{w}(j-1) & \text{otherwise.}
\end{cases}
\]

Based on Proposition 1, we can solve the max–min alignment problem using dynamic programming (see Algorithm MaxMinCluster).

**Algorithm MaxMinCluster**

1. For each subsequence \( M_{ij} \) of \( M \) with \( 1 \leq i \leq j \leq n \), determine whether it is a k-noisy cluster and compute its weight if so. For any \( 1 \leq j \leq n \), let \( S_j \) be the set of all \( i \) values such that \( M_{ij} \) is a k-noisy cluster, and \( i^* \) be the largest such value.
2. Set \( \bar{w}(0) = \bar{w}(0) = \bar{w}(0) = 0 \).
3. For \( j = 1 \) to \( n \)
   (a) For each \( M_{ij} \in S_j \), compute the value according to Proposition 1 part 1 in terms of \( \bar{w}(i-1) \) and \( w(M_{ij}) \).
   (b) Compute \( WE(j) \) according to Proposition 1 part 2 in terms of \( \bar{w}(j-1) \) and \( \bar{w}(h) \) for \( i^* \leq h \leq j - 1 \).
   (c) Set \( \bar{w}(j) = \max \{\bar{w}(j), WE(j)\} \).

Suppose that we have a preprocessing to find all k-noisy clusters and their weights (i.e. Step 1 of Algorithm MaxMinCluster) in \( f(n) \) time so that we can answer in \( O(1) \) time whether a particular segment is a k-noisy cluster. Consider each iteration of Step 3 of Algorithm MaxMinCluster. Computing \( WI(j) \) and \( WE(j) \) takes \( O(j) \) time. Then \( WI(j) \) can be computed in \( O(1) \) time. Therefore, Step 3 of Algorithm MaxMinCluster takes \( O(n^2) \) time and the whole algorithm takes \( O(n^2 + f(n)) \) time.

The preprocessing, i.e. finding all k-noisy clusters, is non-trivial and indeed the bottleneck. Below, we give an algorithm to find all k-noisy clusters with time \( f(n) = O(k^2 n^2) \). In other words, the whole algorithm runs in \( O(k^2 n^2) \) time.

**Finding the k-noisy clusters**

In this section, we show how to find all k-noisy clusters and determine their weights in \( O(k^2 n^2) \) time. A brute-force approach is to determine whether a particular segment \( M_{ij} \) is a k-noisy cluster by examining all possible combinations of up to \( k \) elements in the segment, and checking whether throwing these elements away would leave a sequence satisfying the k-noisy cluster requirement. This requires \( O(n^{k+1}) \) time. Hence, computing all k-noisy clusters and their weights takes \( O(n^{k+3}) \) time. Below we show how to improve the time complexity to \( O(k^2 n^2) \). The main observation is that we are able to determine whether a segment \( M_{ij} \) is a k-noisy cluster by examining a small number of \( M_{ij} \) for some \( j' < j \) that have already been considered. Details are given below.

Consider any \( 1 \leq i \leq j \leq n \). To determine whether a segment \( M_{ij} \) is a k-noisy cluster, we try every \( M_{ij'} \) with \( j' < j \) to check whether it is possible to obtain a k-noisy cluster by extending \( M_{ij'} \) to include \( M_{ij} \) while satisfying the requirements of a k-noisy cluster. We observe that the first three requirements of a k-noisy cluster are local concerns while the fourth requirement (i.e. the size requirement) is a global concern in the following sense. If the segment \( M_{ij} \) does not satisfy the first three requirements, it is impossible to extend it such that \( M_{ij} \) satisfies these requirements. On the other hand, even if \( M_{ij} \) does not satisfy the size requirement, it is still possible to extend \( M_{ij} \) such that \( M_{ij} \) is a k-noisy cluster because adding more matched substring pairs may make the extended segment to be of sufficient size. Based on this observation, we exclude the size requirement when we describe the sub-problem.

Now we describe how to find k-noisy clusters. Recall that \( Gap \) and \( MinSize \) are two predefined positive constants. A set \( H \subset \{m_i, m_{i+1}, \ldots, m_j\} \) is said to be a set of noise in \( M_{ij} \) if \( M_{ij} - H \) satisfies the first three requirements of a noisy cluster (i.e. the size requirement is excluded) and the elements in \( M_{ij} - H \) are either all of the same orientation or all of the opposite orientations (i.e. the value of \( \sigma \) is all the same). Notice that \( \emptyset \) is also a candidate for \( H \). Let \( N_{ij}^+ \) (\( N_{ij}^- \) respectively) be the set of noise \( H \) in \( M_{ij} \) such that all elements in \( M_{ij} - H \) have \( \sigma = 1 \) (\( \sigma = -1 \), respectively). Notice that \( M_{ij} \) is a k-noisy cluster if and only if there is some \( H^* \) in \( N_{ij}^+ \) or \( N_{ij}^- \) such that \( |H^*| \leq k \) and \( \text{Size}(M_{ij} - H^*) \geq \text{MinSize} \). Therefore, we have the following proposition.

**Proposition 2.** \( M_{ij} \) is a k-noisy cluster if and only if the expression

\[
\max \left\{ \max_{H \in N_{ij}^+, \text{Size}(M_{ij} - H) \leq k} \text{Size}(M_{ij} - H), \max_{H \in N_{ij}^-, \text{Size}(M_{ij} - H) \leq k} \text{Size}(M_{ij} - H) \right\}
\]

is at least \( \text{MinSize} \).

Thus, to find all k-noisy clusters, it suffices to compute the expression in Proposition 2 for all \( 1 \leq i \leq j \leq n \). In the rest
of this section, we show how to compute the expression
\[
\max_{H \in \mathbb{N}_0^*; |H| \leq k} \{\text{Size}(M_{ij} - H)\}
\]
for all \(1 \leq i \leq j \leq n\). The counterpart can be computed similarly. Define, for all \(1 \leq i \leq j \leq n\) and \(0 \leq x \leq k\),
\[
\forall(i, j, x) = \max_{H \in \mathbb{N}_0^*; |H| \leq x} \{\text{Size}(M_{ij} - H)\}.
\]

Thus, Expression (1) equals \(\forall(i, j, k)\). Let
\[
\forall(i, j, x) = \max_{H \in \mathbb{N}_0^*; |H| \leq x, m_j \neq H} \{\text{Size}(M_{ij} - H)\}.
\]

To take care of the boundary conditions, for any \(i, j < 1\) and \(x < 0\), we set \(\forall(i, j, x) = \max\{\forall(i, j, x)\}, \forall(i, j, x) = 0\). Then, we have
\[
\forall(i, j, x) = \max\{\forall(i, j, x), \forall(i, j, x - 1)\}.
\]

Now we show how to compute \(\forall(i, j, x)\). If \(m_j\) is of opposite orientations, \(\forall(i, j, x) = 0\). Suppose \(m_j\) is of same orientation. Let \(P\) be the set of matched substring pairs \(m_p = (a_p, b_p, \ell_p)\) such that the following properties are satisfied:
- \(m_p\) is of same orientation;
- \(\max(i, j - x - 1) \leq p \leq j - 1\);
- \(b_p < b_j\); and
- \(m_p\) and \(m_j\) satisfy the distance requirement.\(^2\)

For any \(m_p \in P\), there are \(j - p - 1\) matched substring pairs in between \(m_p\) and \(m_j\). If there is a set \(X\) such that \(|X| \leq x - (j - p - 1)\) and \(M_{ip} - X\) satisfies the first three requirements of noisy cluster, then we can throw away a set \(X'\) with at most \(x\) matched substring pairs from \(M_{ij}\), where \(X' = (m_{p+1}, m_{p+2}, \ldots, m_{j-1}) \cup X\) so that \(M_{ij} - X'\) also satisfies the first three requirements of noisy cluster. Therefore, we have the following proposition.

**Proposition 3.** \(\forall(i, j, x)\) can be computed recursively as follows in terms of \(\forall(i, j', x')\) for some \(j' < j\) and \(x' \leq x\).
\[
\forall(i, j, x) =
\begin{cases}
\max_{m_p \in P} \forall(i, p, x - j + p + 1) + \text{Size}(m(j)) & \text{if } P \neq \emptyset, \\
0 & \text{otherwise}.
\end{cases}
\]

**Time and space complexity** Both the \(\forall\) and \(\forall\) tables have \(kn^2\) entries. Each \(\forall\) entry is the maximum of at most \(k\) precomputed values. Therefore, computing the \(\forall\) table takes \(O(k^2n^2)\) time. Each \(\forall\) entry is the maximum of two precomputed values. Therefore, computing the \(\forall\) table takes \(O(kn^2)\) time. With the computed \(\forall\) values, we can determine whether a given subsequence of \(M\) is a \(k\)-noisy cluster in \(O(1)\) time.

Together with the discussion on computing \(W(j)\), we have a dynamic programming algorithm for the max–min alignment problem which takes \(O(k^2n^2)\) time.

For the space requirement, a straightforward implementation of the dynamic programming requires \(O(kn^2)\) space. We can reduce the requirement to \(O(kn)\) space. Consider the computation of \(W(j)\) for some \(1 \leq j \leq n\). We need to examine the values \(\forall(i, j, k)\) with \(1 \leq i \leq j\). Computing \(\forall(i, j, k)\) requires the computation of \(\forall(i, p, x)\) for some \(0 \leq x \leq k\) and some \(p\) with \(max(i, j - x - 1) \leq p < j\). There are at most \((k + 1)\) such \(x\)-values and at most \((k + 1)\) such \(p\)-values. In other words, the computation of \(W(j)\) requires \(O(k^2n)\) precomputed values, so only \(O(k^2n)\) space is needed to store these values.

**The software tool** By exploiting the MaxMinCluster algorithm, we have developed a software tool for locating conserved genes. The details are as follows.

**Preprocessing** Finding matched substring pairs. We have constructed a program based on suffix tree to find those maximal uniquely matched substring pairs; the running time ranges from several to fifty minutes. We require that each pair of substrings reported has length at least \(\alpha\), for some \(\alpha > 0\). The default value of \(\alpha\) is 20 and 7 for aligning DNA sequences and protein sequences, respectively. As the suffix tree approach sometimes reports a large number of trivially isolated matched substring pairs which are almost certain to be noise, we remove such pairs before the clustering step. The default distance for a trivially isolated pair is set to 8000 and 2000 for DNA sequences and protein sequences, respectively. Note that we purposely make this distance bigger than necessary so as to avoid removing correct matched substring pairs.

**Clustering** We apply the MaxMinCluster algorithm to find an alignment of the matched substring pairs reported before.

**EXPERIMENTAL RESULTS AND DISCUSSION**

In this section, we report the quality of output of MaxMinCluster, and MUMmer-3, on aligning DNA sequences as well as translated protein sequences. We have implemented MaxMinCluster in a PC with 512 M main memory and a 2.4 GHz CPU. We have tested the program on data sets with \(n\) ranges from 30 000 to 100 000 and \(k = 3\).

Notice that MUMmer-3 has two packages: NUCmer is for aligning DNA sequences and PROmer is for translated protein sequences. Both of them share a common clustering algorithm which has similar parameters (Gap and MinSize) as MaxMinCluster. In our experiments, we compare MaxMinCluster with this clustering algorithm on both DNA sequences and translated protein sequences using the same set of parameters.
### Table 1. The coverage, degree of coverage and the sensitivity of aligning the DNA sequences of mouse and human genomes for the setting $\text{Gap} = 2000$ and $\text{MinSize} = 100$

<table>
<thead>
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<th>Exp. No.</th>
<th>Coverage</th>
<th>Degree of coverage</th>
<th>Sensitivity</th>
</tr>
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<tbody>
<tr>
<td></td>
<td>MUMmer</td>
<td>MaxMinCluster</td>
<td>MUMmer</td>
</tr>
<tr>
<td>i</td>
<td>33 (65%)</td>
<td>39 (76%)</td>
<td>50%</td>
</tr>
<tr>
<td>ii</td>
<td>99 (52%)</td>
<td>146 (76%)</td>
<td>40%</td>
</tr>
<tr>
<td>iii</td>
<td>55 (54%)</td>
<td>71 (70%)</td>
<td>48%</td>
</tr>
<tr>
<td>iv</td>
<td>26 (68%)</td>
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<td>73 (78%)</td>
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<tr>
<td>Average</td>
<td>58%</td>
<td>71%</td>
<td>48%</td>
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The figures in parenthesis are the percentage of coverage over the number of published conserved genes.

The data sets we use include ten pairs of mouse and human chromosomes. For each pair of mouse and human chromosomes, a number of conserved genes have already identified by the biological community; details are published in GenBank (see the website http://www.ncbi.nlm.nih.gov/Homology). These published conserved gene will be the reference for our evaluation.

**Measurement**

We evaluate the output of a clustering algorithm from several perspectives: the coverage, the degree of coverage, and the sensitivity. For coverage, we count the number of published conserved genes that overlap with the clusters reported. In addition to coverage, we also measure, for each conserved gene covered, its portion that overlaps with the clusters reported, and we refer the average over all such genes as the degree of coverage.

Notice that high coverage alone may not imply high-quality output as an algorithm can simply output all matched substring pairs as a single cluster, thus achieving the highest possible coverage and degree of coverage. Therefore, we also measure the percentage of the clusters reported that actually cover the published conserved genes. This percentage is referred to as the sensitivity. It gives us an indicator of the accuracy, yet it may underestimate the actual accuracy as not all conserved genes have been identified. In other words, we expect a good algorithm to produce a set of clusters with high coverage and reasonable sensitivity.

**Aligning DNA sequences**

We present the results on aligning DNA sequences of mouse and human chromosomes. The chromosomes used in our experiments are of lengths from 14 million to 65 million nucleotides. In finding matched substring pairs, we require that each pair of substrings reported has lengths at least 20. Substring pairs with lengths less than 20 are likely to be noise (Delcher et al., 1999). These substring pairs serve as the input data to our algorithm as well as MUMmer. The details of the data sets are given in the Appendix.

**The findings**

We have analyzed the data and observed that the average gap between adjacent matched substrings within a conserved gene ranges from 1000 to 3000 nucleotides, and the total length of matched substrings ranges from tens to hundreds. Therefore, we have performed experiments using different $\text{Gap}$ and $\text{MinSize}$ values. The results reveal that (1) MaxMinCluster reports more conserved genes than MUMmer in all settings, and (2) a sensible setting for MUMmer, as well as for MaxMinCluster, is to let $\text{Gap} = 2000$ and $\text{MinSize} = 100$.

Table 1 shows the coverage, degree of coverage and sensitivity of the output for the setting $\text{Gap} = 2000$ and $\text{MinSize} = 100$. In each data set, MaxMinCluster has a higher coverage than MUMmer, the average improves from 58 to 71%. It is evident that the global selection criterion is effective. The output from MaxMinCluster also shows a higher degree of coverage than MUMmer. Regarding sensitivity, both software tools are reasonable, though MaxMinCluster is slightly higher.

In conclusion, MaxMinCluster, based on a global selection criterion and the noise tolerance feature, is able to produce a set of clusters of higher quality.

**Different $\text{Gap}$ and $\text{MinSize}$ values**

We have also tested the algorithms with different values of $\text{Gap}$ and $\text{MinSize}$. Firstly, we fix $\text{MinSize}$ to 100 and vary $\text{Gap}$ for 100, 300, 600, 1000, 2000 and 3000 (Fig. 2). The results show that coverage, degree of coverage and sensitivity increase as the value of $\text{Gap}$ increases, yet increasing the value of $\text{Gap}$ beyond 2000 gives no significant improvement in coverage and sensitivity.
Fig. 2. The effect of varying the Gap value on coverage, degree of coverage and sensitivity (MinSize is fixed to 100) on aligning DNA sequences of mouse and human genomes.

Fig. 3. The effect of varying the MinSize value on coverage, degree of coverage and sensitivity (Gap is fixed to 2000) on aligning DNA sequences of mouse and human genomes.
Secondly, we fix Gap to 2000 and vary MinSize for 60, 80, 100, 120, 140, 200 and 300 (Fig. 3). The results show that sensitivity increases as the value of MinSize increases, while coverage and degree of coverage decrease as expected. Furthermore, increasing the value of MinSize beyond 100 gives no significant improvement in sensitivity. Therefore, Gap = 2000 and MinSize = 100 is a sensible choice to obtain a high coverage while maintaining a high sensitivity.

Running time and memory requirement We have measured the actual running time and memory requirement of MaxMinCluster and MUMmer-3 for the ten sets of data. As expected, MUMmer-3, based on a linear time heuristic, is much faster and requires much less memory. The average running time is about one second and the average memory requirement is about two megabytes. On the other hand, MaxMinCluster is much slower and requires more memory as it uses a quadratic time algorithm to solve the optimization problem optimally. Nevertheless, the actual running time of MaxMinCluster ranges from several seconds to ten minutes and the actual memory requirement ranges from tens to hundred megabytes; this is acceptable in most applications.

Aligning translated protein sequences
Both MaxMinCluster and MUMmer-3 can be used to align the translated protein sequences of different genomes. Aligning on protein level is significant when the species are more distant because these species usually show much higher similarity on protein level than on nucleotide level.

We have run MaxMinCluster and MUMmer-3 on the translated protein sequences of the ten pairs of mouse and human chromosomes. We find that the translated protein sequences show much higher similarity and both MaxMinCluster and MUMmer-3 achieve very high coverage. In particular, based on the setting with matched substrings containing at least 7 amino acids (∼20 nt), Gap = 666 (∼2000 nt), and MinSize = 33 (∼100 nt), MaxMinCluster and MUMmer-3 both achieves an average coverage of 92%; the sensitivity is 32 and 30%, respectively.

The high-coverage result above triggers us to further analyze the conserved genes. We found that in protein level, the clusters residing in most conserved genes are quite obvious and this explains why both software tools can obtain a high coverage. To better understand the performance of MaxMinCluster and MUMmer-3 on aligning protein sequences, we perform experiments on aligning nine virus genomes, which do not show a high level of similarity as human and mouse. These virus genomes and the corresponding conserved genes have been published in the literature (Herniou et al., 2001 http://www.bio.ic.ac.uk/research/dor/research/eah). See the Appendix for more details. These genomes are of length from 100 000 nt to 200 000 nt. We translate the sequences into amino acid sequences and use the suffix tree program to locate matched substring pairs with at least three amino acids.

We have run MaxMinCluster and MUMmer-3 using different parameters. A sensible setting is MinSize = 8, and the distance requirement has Diff = 5 and Ratio = 0.1. The coverage and sensitivity of MaxMinCluster and MUMmer-3 are shown in Figure 4. In general, the coverage of MaxMinCluster is higher than MUMmer, the average is 57 and 54% respectively; the average sensitivity of the two software tools is almost the same, which is ∼66%.

Remarks We have also aligned the DNA sequences of the nine virus genomes but find that most of them show very low similarity. Both MUMmer-3 and MaxMinCluster are able to uncover only very few conserved genes, indeed, for quite a number of virus pairs, no matched substring pairs can be found, not to mention conserved genes.

REFERENCES
APPENDIX
Details of the data sets for mouse and human chromosmes

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<th>Mouse Chr no.</th>
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Details of the data sets for virus genomes

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