

Moment-Based Fast Discrete Sine Transforms

J. G. Liu, F. H. Y. Chan, F. K. Lam, and H. F. Li

Abstract—This paper presents a novel approach to compute discrete sine transforms (DST's). By using a modular mapping, DST's are approximated by the sum of a finite sequence of discrete moments. Hence, by extending our earlier technique in computing moments with an adder network only, DST's can also be implemented easily by a systolic array primarily involving additions. The method can be applied to multidimensional DST's as well as their inverses.

Index Terms—Discrete sine transforms, fast transformation, moment, systolic array.

DISCRETE sine transforms (DST's) are widely used in speech coding and image compression.

The N -point DST-II is defined by the equations

$$X(k) = \sum_{n=1}^N x(n) \sin(\pi(2n-1)k/2N) \quad 1 \leq k \leq N \quad (1)$$

where

$$c_k = \begin{cases} 1/\sqrt{N}, & \text{for } k = N \\ \sqrt{2/N}, & \text{otherwise.} \end{cases}$$

Let us simplify (1). By using the periodic property and other properties of sine functions, we have

$$\sin(\pi(2n-1)k/2N) = \sin(i\pi/2N)$$

or

$$-\sin(i\pi/2N) \quad 0 \leq i \leq N, 1 \leq k \leq N.$$

For every pair of k and i ($i, k = 1, 2, \dots, N$), defining $S(k, i)$ and $s(k, i)$ by

$$\begin{aligned} S(k, i) &= \{j \mid \sin(\pi(2j-1)k/2N) \\ &\quad = \sin(i\pi/2N) \quad 1 \leq j \leq N\} \\ s(k, i) &= \{j \mid \sin(\pi(2j-1)k/2N) \\ &\quad = -\sin(i\pi/2N) \quad 1 \leq j \leq N\} \end{aligned}$$

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then defining $x_{k,i}(i, k = 0, 1, 2, \dots, N-1)$ by

$$x_{k,i} = \begin{cases} \sum_{j \in S(k,i)} x(j) - \sum_{j \in s(k,i)} x(j) & S(k, i) \cup s(k, i) \neq \emptyset, \\ 0, & \text{otherwise.} \end{cases} \quad i, k = 1, 2, \dots, N \quad (2)$$

Thus, by direct substitution, (1) can be rewritten as follows:

$$X(k) = c_k \sum_{i=1}^N x_{k,i} \sin(\pi i/2N) \quad 1 \leq k \leq N. \quad (3)$$

For $1 \leq i \leq N-1$

$$\begin{aligned} \sin(\pi i/2N) &= (\pi i/2N) - (\pi i/2N)^3/3! \\ &\quad + \dots + (-1)^p (\pi i/2N)^{2p+1}/(2p+1)! + R_i \\ R_i &= \sin(\xi_i + (p+2)\pi/2) \\ &\quad \cdot (\pi i/2N)^{2p+2}/(2p+2)! \quad 0 < \xi_i < \pi i/2N. \end{aligned} \quad (4)$$

This follows immediately by applying the theorem of extended law of the mean to $\sin(\pi i/N)$, where R_i is a Taylor remainder term. Substituting (4) into (3) yields

$$\begin{aligned} X(k) &= c_k \sum_{i=1}^{N-1} x_{k,i} \sum_{r=0}^p (-1)^r (\pi i/2N)^{2r+1}/ \\ &\quad \cdot (2r+1)! + c_k x_{k,N} + R_p \\ &= c_k \sum_{r=0}^p (-1)^r \pi^{2r+1}/(2N)^{2r+1} (2r+1)! \\ &\quad \cdot \sum_{i=1}^{N-1} x_{k,i} i^{2r+1} + c_k x_{k,N} + R_p \quad 1 \leq k \leq N \\ &= c_k \sum_{r=0}^p a_r m_{k,2r+1} + c_k x_{k,N} + R_p \end{aligned} \quad (5)$$

where

$$a_r = (-1)^r \pi^{2r+1}/(2N)^{2r+1} (2r+1)! \quad (6)$$

$$m_{k,2r+1} = \sum_{i=1}^{N-1} x_{k,i} i^{2r+1} \quad (7)$$

$$\begin{aligned} R_p &= c_k \sum_{i=1}^{N-1} x_{k,i} \sin(\xi_i + (p+1)\pi) \\ &\quad \cdot (\pi i/2N)^{2p+2}/(2p+2)! \quad 0 < \xi_i < \pi i/2N. \end{aligned} \quad (8)$$

If R_p is ignored, we have

$$X(k) = c_k \left(x_{k,N} + \sum_{r=0}^p a_r m_{k,2r+1} \right) \quad 1 \leq k \leq N. \quad (9)$$

The absolute value of the error introduced by overlooking R_p is bounded by

$$|R_p| \leq \max_n |x(n)| c_k (N-1) \pi^{2p+2} / 2^{2p+2} (2p+2)! \quad (10)$$

From the inequality above, it is clearly shown that R_p converges to zero very rapidly and uniformly. For example, for $\max|x(n)| \leq 256$, $(0 \leq n \leq N-1)$, $N \leq 2048$, $p = 8$

$$|R_p| \leq 8.32 \times 10^{-9}.$$

This error can satisfy accuracy requirements of most applications. Furthermore, we can prove that the least upper bound of p is not more than $O(\log_2 N / \log_2 \log_2 N)$ as N tends to infinite [1], [2].

The N -point DST-I is defined by the equations

$$X(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^{N-1} x(n) \sin \frac{kn\pi}{N} \quad 1 \leq k \leq N-1. \quad (11)$$

By using the periodic property and other properties of sine functions, we have

$$\sin(kn\pi/N) = \sin(i\pi/N)$$

or

$$-\sin(i\pi/N) \quad 1 \leq i \leq N, 1 \leq k \leq N-1.$$

For every pair of k and i ($i, k = 1, 2, \dots, N$), defining $S(k, i)$ and $s(k, i)$ by

$$\begin{aligned} S(k, i) &= \{j \mid \sin(kj\pi/N) \\ &= \sin(i\pi/N) \quad 1 \leq j \leq N-1\} \\ s(k, i) &= \{j \mid \sin(kj\pi/N) \\ &= -\sin(i\pi/N) \quad 1 \leq j \leq N-1\} \end{aligned}$$

then defining $x_{k,i}$ ($i, k = 0, 1, 2, \dots, N-1$) by

$$x_{k,i} = \begin{cases} \sum_{j \in S(k,i)} x(j) - \sum_{j \in s(k,i)} x(j) & i, k = 1, 2, \dots, N \\ 0, & \text{otherwise.} \end{cases} \quad (12)$$

Thus, by direct substitution, (11) can be rewritten as follows:

$$X(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^{N-1} x_{k,1} \sin \frac{i\pi}{N} \quad 1 \leq k \leq N-1. \quad (13)$$

The N -point DST-III is defined by the equations

$$X(k) = \sqrt{\frac{2}{N}} \sum_{n=1}^{N-1} C_n x(n) \sin \frac{(2k-1)n\pi}{2N} \quad 1 \leq k \leq N \quad (14)$$

where

$$c_n = \begin{cases} 1/\sqrt{N}, & \text{for } n = N \\ \sqrt{2/N}, & \text{otherwise.} \end{cases}$$

By using the periodic property and other properties of sine functions, we have

$$\sin(\pi(2k-1)n/2N) = \sin(i\pi/2N)$$

or

$$-\sin(i\pi/2N) \quad 0 \leq i \leq N, 1 \leq k \leq N.$$

For every pair of k and i ($i, k = 1, 2, \dots, N$), defining $S(k, i)$ and $s(k, i)$ by

$$\begin{aligned} S(k, i) &= \{j \mid \sin(\pi(2k-1)j/2N) \\ &= \sin(i\pi/2N) \quad 1 \leq j \leq N\} \\ s(k, i) &= \{j \mid \sin(\pi(2k-1)j/2N) \\ &= -\sin(i\pi/2N) \quad 1 \leq j \leq N\} \end{aligned}$$

then defining $x_{k,i}$ ($i, k = 0, 1, 2, \dots, N-1$) by

$$x_{k,i} = \begin{cases} \sum_{j \in S(k,i)} C_j x(j) & \\ -\sum_{j \in s(k,i)} C_j x(j) & \\ S(k, i) \cup s(k, i) \neq \phi, & i, k = 1, 2, \dots, N \\ 0, & \text{otherwise.} \end{cases} \quad (15)$$

Thus

$$X(k) = \sum_{n=1}^{N-1} x_{k,1} \sin \frac{i\pi}{2N} \quad 0 \leq k \leq N. \quad (16)$$

The N -point DST-IV is defined by the equations

$$\begin{aligned} X(k) &= \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x(n) \sin \\ &\cdot \frac{(2k+1)(2n+1)\pi}{4N} \quad 1 \leq k \leq N-1. \end{aligned} \quad (17)$$

By using the periodic property and other properties of sine functions, we have

$$\begin{aligned} &\sin(2k+1)(2n+1)\pi/4N \\ &= \sin(i\pi/4N) \text{ or } -\sin(i\pi/4N) \text{ or} \\ &\cos(i\pi/4N) \text{ or } -\cos(i\pi/4N) \\ &0 \leq i \leq N, 1 \leq k \leq N-1. \end{aligned}$$

For every pair of k and i ($i, k = 1, 2, \dots, N$), defining $S(k, i)$, $s(k, i)$, $C(k, i)$, $c(k, i)$ by

$$\begin{aligned} S(k, i) &= \{j \mid \sin(2k+1)(2j+1)\pi/4N \\ &= \sin(i\pi/4N) \quad 1 \leq j \leq N-1\} \\ s(k, i) &= \{j \mid \sin(2k+1)(2j+1)\pi/4N \\ &= -\sin(i\pi/4N) \quad 1 \leq j \leq N-1\} \end{aligned}$$

$$\begin{aligned} C(k, i) &= \{j | \sin(2k+1)(2j+1)\pi/4N \\ &\quad = \cos(i\pi/4N) \quad 1 \leq j \leq N-1\} \\ c(k, i) &= \{j | \sin(2k+1)(2j+1)\pi/4N \\ &\quad = -\cos(i\pi/4N) \quad 1 \leq j \leq N-1\} \end{aligned}$$

then defining $x_{k,i}$ and $y_{k,i}$ ($i = 0, 1, 2, \dots, N-1$) by

$$x_{k,i} = \begin{cases} \sum_{j \in S(k,i)} x(j) \\ - \sum_{j \in s(k,i)} x(j) \\ S(k, i) \cup s(k, i) \neq \emptyset, \quad i, k = 0, 1, 2, \\ \dots, N-1 \\ 0, \quad \text{otherwise.} \end{cases} \quad (18)$$

$$y_{k,i} = \begin{cases} \sum_{j \in S(k,i)} x(j) \\ - \sum_{j \in s(k,i)} x(j) \\ C(k, i) \cup c(k, i) \neq \emptyset, \quad i, k = 0, 1, 2, \\ \dots, N-1 \\ 0, \quad \text{otherwise.} \end{cases} \quad (19)$$

Thus

$$\begin{aligned} X(k) &= \sum_{n=1}^{N-1} \mathbf{x}_{k,i} \sin \frac{i\pi}{4N} \\ &\quad + \sum_{n=0}^{N-1} \mathbf{y}_{k,i} \cos \frac{i\pi}{4N} \quad 0 \leq k \leq N-1. \end{aligned} \quad (20)$$

If applied the theorem of extended law of the mean, (13), (16), and (20) can be transformed into the forms of (9). In other

words, an additional three forms of DST could also be computed through computation of moments. They have the same error levels and the same convergence features.

Equation (9) contains the formulas of the relationship between DST and moments. According to it, the computation of $X(k)$ requires the generation of the $2r+1$ th order moments of the transformed data sequence $x_{k,i}$, followed by computing the dot-product of between this and a constant vector (a_r) and an addition with $x_{k,N}$, finally followed by a multiplication with c_k . The efficiency of the procedure largely depends on the efficiency in deriving the moments. We have presented an approach to moments of computation that involves in just additions and designed systolic arrays implementing the method [3], [4].

The proposed method has several noteworthy advantages. First, most multiplications are replaced by additions, and triangular functions are replaced with simple polynomial functions. Second, the multiplication number for one-dimensional (1-D) DST in our method is $O(N \log_2 N / \log_2 \log_2 N)$ superior to $O(N \log_2 N)$ needed in conventional fast sine transform. Third, the algorithm can be directly realized in the form of a systolic array for real-time applications. Fourth, the method is easily extendable to multidimensional DST's as well as their inverses. The computational complexity for k -dimensional DST is $O(n^k)$.

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