# SOLUTION TO TIME-ENERGY COSTS OF QUANTUM CHANNELS

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We derive a formula for the time-energy costs of general quantum channels proposed in [Phys. Rev. A 88, 012307 (2013)]. This formula allows us to numerically find the time-energy cost of any quantum channel using positive semidefinite programming. We also derive a lower bound to the time-energy cost for any channels and the exact the time-energy cost for a class of channels which includes the qudit depolarizing channels and projector channels as special cases.

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### 1 Introduction

A time-energy cost of a unitary matrix  $U \in U(r)$  is defined as [1]

$$||U||_{\max} = \max_{1 \le j \le r} |\theta_j| \tag{1}$$

where U has eigenvalues  $\exp(i\theta_j)$  for j = 1, ..., r. Here, we denote by U(r) the group of  $r \times r$  unitary matrices, and we take the convention that  $\theta_j \in (-\pi, \pi]$ . This definition of time-energy cost was motivated [1, 2] from time-energy uncertainty relations [3, 4]. Essentially, this time-energy cost captures the idea that time and energy are a trade-off against each other and may be used as an indicator for the resource used by a quantum system. In particular,

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a closed quantum system with a time-independent Hamiltonian H evolves from the initial state  $|\psi_i\rangle$  to the final state  $|\psi_f\rangle$  according to the Schrödinger equation:  $|\psi_f\rangle = U|\psi_i\rangle$  where  $U = \exp(-iHt/\hbar)$  and t is the evolution time. The eigenvalues of the Hamiltonian H are the energies and thus the eigenvalues of  $\log U$  correspond to the time-energy products, the absolute maximum of which is the time-energy cost  $||U||_{\max}$  defined above. Note that to implement the same information processing task characterized by U, one may use a high energy H run for a short time or a low energy H run for a long time. The time-energy products in both cases are the same.

The definition for  $||U||_{\text{max}}$  in Eq. (1) is for unitary quantum channels. The time-energy cost has been extended to cover general quantum channels [2]. A quantum channel mapping n-dimensional density matrices to n-dimensional density matrices can be written as

$$\mathcal{K}(\rho) = \sum_{j=1}^{d} K_j \rho K_j^{\dagger},\tag{2}$$

where  $K_j \in \mathbb{C}^{n \times n}$  are the Kraus operators and  $\sum_{j=1}^d K_j^{\dagger} K_j = I_n$ . In this paper, we only consider finite dimensional systems. The time-energy cost for quantum channel  $\mathcal{K}$  is defined as the time-energy cost of the most efficient unitary extension that implements  $\mathcal{K}$  [2]:

$$\|\mathcal{K}\|_{\max} \equiv \min_{U} \|U\|_{\max} \tag{3}$$

s.t. 
$$\mathcal{K}(\rho) = \text{Tr}_B[U_{BA}(|0\rangle_B\langle 0|\otimes \rho_A)U_{BA}^{\dagger}] \,\forall \rho,$$

where the channel K acts on quantum state  $\rho$  in system A and the unitary extension  $U_{BA}$  includes system B prepared in a standard state.

The time-energy cost has an interesting informational meaning. The cosine of this cost for a general quantum channel is exactly the worst-case entanglement fidelity of the channel [5], establishing a connection between the physical aspect (the time-energy cost) and the information aspect (the fidelity) of quantum channels. Fidelity is a popular quantity often used to characterize the performance of information processing tasks including quantum key distribution (as a security measure [6, 7]) and state discrimination (as the inconclusive probability [8, 9, 10]). Thus the study of the time-energy cost is important from a quantum information theoretical perspective. To be specific, the result of Ref. [5] shows that for any quantum channel  $\mathcal{K}$ , the worst-case entanglement fidelity  $F_{\min}(\mathcal{K})$  of the channel is related to the time-energy cost by

$$F_{\min}(\mathcal{K}) = \cos \|\mathcal{K}\|_{\max}. \tag{4}$$

Here, the worst-case entanglement fidelity  $F_{\min}(\mathcal{K})$  is defined as

$$F_{\min}(\mathcal{K}) \equiv \min_{|\Psi\rangle} F(|\Psi\rangle_{AC} \langle \Psi|, (\mathcal{K}_A \otimes I_C)(|\Psi\rangle_{AC} \langle \Psi|)), \tag{5}$$

where the channel acts on system A and the fidelity is taken between the channel input state (allowed to be entangled in systems A and C) and the corresponding output state. Here,  $F(\rho, \rho') \equiv \text{Tr} \sqrt{\rho^{1/2} \rho' \rho^{1/2}}$  is the fidelity between two mixed quantum states  $\rho$  and  $\rho'$  [11, 12].

 $<sup>\</sup>overline{b}$  Note that Ref. [5] originally shows that  $F_{\min}(\mathcal{K}) = \max(\cos \|\mathcal{K}\|_{\max}, 0)$ . However, we should always consider taking the freedom of including an all-zero Kraus operator in the channel representation. In this case,  $\cos \|\mathcal{K}\|_{\max}$  is never negative. See Theorem 1 and its proof.

This paper derives a formula for the time-energy cost  $\|\mathcal{K}\|_{\max}$  defined in Eq. (3) and provides a numerical solution method via semidefinite programming. This in turn allows us to compute the the worst-case entanglement fidelity using Eq. (4). The difficulty in solving for  $\|\mathcal{K}\|_{\max}$  stems from the freedom in the unitary extension. All the freedom we have for choosing different U without changing the channel consists of the following operations:

- 1. Change the last (d+1)n n columns of U.
- 2. Apply  $V \otimes I_n$  to U on the left, where  $V \in U(d+1)$ .

It turns out that one can apply an abstract mathematical result in unitary dilation theory [13] to solve the problem. One can then determine the optimal solution using semidefinite programming. Thus, we have a theoretical optimal solution that can be determined by numerical method. This is one of the best scenarios in solving an optimization problem if there is a closed form for the optimal solution of the given problem.

The organization of this paper is as follows. We solve problem (3) for  $\|\mathcal{K}\|_{\max}$  in Sec. 2, and we derive a lower bound to the time-energy cost for any channels and compute the exact time-energy costs for special channels in Sec. 3. We formulate in Sec. 4 the problem of finding the time-energy cost as a semidefinite program (SDP) which can be solved numerically and efficiently. We give some mathematical remarks in Sec. 5 and conclude in Sec. 6

### Main result

Theorem 1

$$\|\mathcal{K}\|_{\max} = \cos^{-1} \left[ \max_{\mathbf{v}} \frac{1}{2} \lambda_{\min} \left( K_{\mathbf{v}} + K_{\mathbf{v}}^{\dagger} \right) \right]$$
 (6)

where  $\mathbf{v} \in \mathbb{C}^d$  has  $\ell_2$ -norm  $\|\mathbf{v}\| \leq 1$ ,  $K_{\mathbf{v}} = \sum_{j=1}^d v_j K_j$ ,  $\lambda_{\min}(\cdot)$  denotes the minimum eigenvalue of its argument, and we take the convention that  $\cos^{-1}$  returns an angle in the range  $[0,\pi].$ 

**Proof:** The most general form of U in Eq. (3) is

$$U = (V \otimes I_n) \underbrace{\begin{bmatrix} K_1 & * & * & \cdots & * \\ K_2 & * & * & \cdots & * \\ \vdots & & & \vdots \\ K_d & * & * & \cdots & * \\ K_{d+1} & * & * & \cdots & * \end{bmatrix}}_{U'}$$
(7)

where  $V \in U(d+1)$  and only the first n columns of U' are fixed. Here, we append an all-zero Kraus operator  $K_{d+1} = 0$  in order to make U the most general unitary implementing the channel K. Certainly, both  $\{K_1, \ldots, K_d\}$  and  $\{K_1, \ldots, K_{d+1}\}$  are valid representations of K. As we shall see, there is no need to add more than one extra all-zero operator.

We first consider the freedom in U'. Let d' = d + 1. We want to choose the last d'n - ncolumns of U' so that its norm is the smallest. This is described as an optimization problem as follows:

$$\varphi \equiv \min_{U'} \|U'\|_{\text{max}}$$
s.t.  $U'_{i1} = K_i$  for all  $i = 1, \dots, d'$ ,
with  $U' \in \mathcal{U}(d'n)$  (8)

where  $U'_{ij}$  denotes the (i,j) block of size  $n \times n$ .

By the result in Ref. [13], we know that there is a unitary matrix  $\tilde{U} = (\tilde{U}_{rs})_{1 \leq r,s \leq 2} \in U(2n)$  with eigenvalues  $e^{\pm i\theta_j}$  for  $j = 1, \ldots, n$ , such that  $\tilde{U}_{11} = K_1$  and  $\tilde{U}_{21} = \sqrt{I_n - K_1^{\dagger} K_1}$  where  $\pi \geq \theta_1 \geq \cdots \geq \theta_n \geq 0$  and  $\cos(\theta_1) = \lambda_{\min}(K_1 + K_1^{\dagger})/2$ . Note that there exists  $W \in U(d'n - n)$  such that  $(I_n \oplus W)(\tilde{U} \oplus I_{d'n-2n})(I_n \oplus W)^{\dagger}$  satisfies the constraints in Eq. (8) and thus

$$\varphi \le \left\| \tilde{U} \right\|_{\text{max}} = \cos^{-1} \left[ \frac{1}{2} \lambda_{\min} \left( K_1 + K_1^{\dagger} \right) \right]. \tag{9}$$

Next, we lower bound  $\varphi$ . Consider U' satisfying the constraints in Eq. (8). By the interlacing inequalities (see, e.g., Ref. [14]), because  $(K_1 + K_1^{\dagger})/2$  is the principal submatrix of  $(U' + U'^{\dagger})/2$ , the eigenvalues  $a_1 \geq \cdots \geq a_{d'n}$  of  $(U' + U'^{\dagger})/2$  and the eigenvalues  $b_1 \geq \cdots \geq b_n$  of  $(K_1 + K_1^{\dagger})/2$  satisfy

$$a_{d'n} \le b_n \le a_n$$

and so

$$\cos^{-1}(a_{d'n}) \ge \cos^{-1}(b_n).$$

If U' has eigenvalues  $\exp(i\theta_j)$ , where  $j=1,\ldots,d'n$  and  $\theta_j \in (-\pi,\pi]$ , then  $a_{d'n}=\cos(\max_j |\theta_j|)$ , giving

$$\max_{j} |\theta_{j}| \ge \cos^{-1} \left[ \frac{1}{2} \lambda_{\min} \left( K_{1} + K_{1}^{\dagger} \right) \right].$$

Thus, (8) is bounded by

$$\varphi \ge \cos^{-1} \left[ \frac{1}{2} \lambda_{\min} \left( K_1 + K_1^{\dagger} \right) \right]. \tag{10}$$

Combining with Eq. (9) gives

$$\varphi = \cos^{-1} \left[ \frac{1}{2} \lambda_{\min} \left( K_1 + K_1^{\dagger} \right) \right]. \tag{11}$$

Finally, we optimize V in Eq. (7) to obtain  $\|\mathcal{K}\|_{\text{max}}$ . Note that  $\varphi$  which corresponds to the optimal solution of U' after adjusting the last d'n - n columns depends only on the principal submatrix of U'. Thus,

$$\|\mathcal{K}\|_{\max} = \cos^{-1} \left[ \max_{\mathbf{v}: \|\mathbf{v}\| = 1} \frac{1}{2} \lambda_{\min} \left( K_{\mathbf{v}} + K_{\mathbf{v}}^{\dagger} \right) \right]$$
 (12)

where  $\mathbf{v} \in \mathbb{C}^{d+1}$  is the first row of V. Here,  $K_{\mathbf{v}} = \sum_{j=1}^{d+1} v_j K_j$  represents the principal submatrix of U, where  $\mathbf{v} = [v_1, \dots, v_{d+1}]$ . Taking into account  $K_{d+1} = 0$  gives the claim of the theorem.  $\square$ 

We remark that  $\cos \|\mathcal{K}\|_{\max} \geq 0$ .

# Time-energy costs for special channels

In this section, we use Theorem 1 to compute the time-energy costs for a class of channels which includes the qudit depolarizing channels and projector channels as special cases.

**Lemma 1** Any channel  $\mathcal{K}$  can be described by an equivalent form with the Kraus operators  $\{K_j \in \mathbb{C}^{n \times n} : j = 1, \dots, d\}$  satisfying

$$Tr(K_i) = 0, \ i = 2, ..., d.$$

**Proof:** Two sets of Kraus operators  $\{K_1, \ldots, K_d\}$  and  $\{\tilde{K}_1, \ldots, \tilde{K}_d\}$  describe the same quantum channel if and only if

$$K_i = \sum_{j=1}^{d} w_{ij} \tilde{K}_j, \text{ for } i = 1, \dots, d$$
 (13)

and for some unitary matrix  $W \equiv [w_{ij}]$  of dimension d (see, e.g., Theorem 8.2 of Ref. [15]). By taking the trace of Eq. (13), we see that there must exist W that can bring d-1 terms to zero. In particular, we have

$$K_{1} = \left(\sum_{j=1}^{d} |\text{Tr}(\tilde{K}_{j})|^{2}\right)^{-\frac{1}{2}} \sum_{j=1}^{d} \text{Tr}^{\dagger}(\tilde{K}_{j})\tilde{K}_{j}.$$
 (14)

(If d = 1, we can pad the channel with  $K_2 = 0$  to make Lemma 1 automatically hold.)

**Lemma 2** For any channel K that can be described by Kraus operators  $\{K_j \in \mathbb{C}^{n \times n} : j = 1\}$  $1, \ldots, d$  of the form

$$Tr(K_i) = 0, \ j = 2, \dots, d,$$

we have

$$\cos^{-1}\left[\frac{1}{n}\left|\operatorname{Tr}\left(K_{1}\right)\right|\right] \leq \left\|\mathcal{K}\right\|_{\max}.\tag{15}$$

**Proof:** We consider the middle term of Eq. (6):

$$\frac{1}{2}\lambda_{\min}\left(K_{\mathbf{v}} + K_{\mathbf{v}}^{\dagger}\right) \leq \frac{1}{2n}\sum_{i=1}^{n}\lambda_{i}\left(K_{\mathbf{v}} + K_{\mathbf{v}}^{\dagger}\right)$$

$$= \frac{1}{2n}\operatorname{Tr}\left(K_{\mathbf{v}} + K_{\mathbf{v}}^{\dagger}\right)$$

$$= \frac{1}{n}\operatorname{Re}\left[\operatorname{Tr}\left(K_{\mathbf{v}}\right)\right]$$

$$= \frac{1}{n}\operatorname{Re}\left[v_{1}\operatorname{Tr}\left(K_{1}\right)\right]$$

where the first line is because the minimum is no greater than the average and  $\lambda_i$  denotes the ith eigenvalue. Maximizing over  $\mathbf{v}$  gives the claim.  $\square$ 

**Theorem 2 (Time-energy lower bound)** For any channel  $\mathcal{K}$  described by Kraus operators  $\{K_j \in \mathbb{C}^{n \times n} : j = 1, \dots, d\}$ , we have

$$\cos^{-1}\left[\frac{1}{n}\sqrt{\sum_{j=1}^{d}\left|\operatorname{Tr}\left(K_{j}\right)\right|^{2}}\right] \leq \left\|\mathcal{K}\right\|_{\max}.$$
(16)

**Proof:** This follows from Lemma 1 and Lemma 2.  $\square$ 

Theorem 3 (Time-energy for special channels) For any channel K that can be described by Kraus operators  $\{K_j \in \mathbb{C}^{n \times n} : j = 1, ..., d\}$  of the form

$$K_1 = \alpha I \text{ where } \alpha \in \mathbb{C}$$
  
 $\text{Tr}(K_j) = 0, \ j = 2, \dots, d,$  (17)

its time-energy cost is

$$\|\mathcal{K}\|_{\text{max}} = \cos^{-1}|\alpha|. \tag{18}$$

**Proof:** From Eq. (15), we have  $\cos^{-1} |\alpha| \le ||\mathcal{K}||_{\max}$ .

On the other hand, by choosing a particular  $\mathbf{v}$ ,

$$\max_{\mathbf{v}} \frac{1}{2} \lambda_{\min} \left( K_{\mathbf{v}} + K_{\mathbf{v}}^{\dagger} \right)$$

$$\geq \max_{\theta_1} \frac{1}{2} \lambda_{\min} \left( e^{i\theta_1} K_1 + e^{-i\theta_1} K_1^{\dagger} \right)$$

$$= |\alpha|.$$

Therefore,  $\|\mathcal{K}\|_{\max} \leq \cos^{-1} |\alpha|$  and the claim is proved.  $\square$ 

Note that this theorem is slightly more general than Eq. (52) of Ref. [2] in which  $\alpha$  is real and positive. As noted in Ref. [2], channels satisfying Eq. (17) include the qudit depolarizing channels. In the following, we show that projector channels also satisfy Eq. (17).

In general, given a channel, we can find an equivalent form according to Lemma 1 and compute the new  $K_1$  using Eq. (14). If this new  $K_1$  satisfies Eq. (17), then the time-energy cost of the channel is immediately given by Theorem 3. Otherwise, we can lower bound it using Theorem 2.

**Theorem 4 (Projector channels)** For any channel  $\mathcal{K}$  that can be described by Kraus operators  $\{K_j \in \mathbb{C}^{n \times n} : j = 1, ..., d\}$  of the form  $K_j = s_j P_j$  with  $P_j = P_j^2 = P_j^{\dagger}$  being a projector of rank r and  $s_j \in \mathbb{C}$ , we have

$$\|\mathcal{K}\|_{\max} = \cos^{-1}\left(\sqrt{\frac{r}{n}}\right). \tag{19}$$

**Proof:** Note that  $Tr(K_j) = s_j r$  for all j. Using Lemma 1 and Eq. (14), an equivalent description of K satisfies

$$K'_{1} = \frac{1}{\sqrt{\sum_{i=1}^{d} |s_{i}|^{2}}} I,$$
$$Tr(K'_{j}) = 0, \ j = 2, \dots, d.$$

Next, note that the trace-preserving constraint of quantum channels implies that  $I_n = \sum_{j=1}^d K_j^{\dagger} K_j = \sum_{j=1}^d |s_j|^2 P_j$  and taking the trace of it gives  $n/r = \sum_{j=1}^d |s_j|^2$ . Then by Theorem 3, the claim is proved.  $\square$ 

### 4 Efficient numerical solution using semidefinite programming

Our main result (6) in Theorem 1 can be formulated as an SDP. We can write  $K_j = A_j + iB_j$ , where  $A_j, B_j \in \mathbb{C}^{n \times n}$  are Hermitian, and also write  $v_j = a_j - ib_j$  with  $a_j, b_j \in \mathbb{R}$  for  $j = a_j - ib_j$  $1, \ldots, d$ . Then the problem is equivalent to

$$\max \qquad \lambda_{\min} \left( \sum_{i=1}^{d} (a_j A_j + b_j B_j) \right)$$
s.t. 
$$\sum_{j=1}^{d} (a_j^2 + b_j^2) \le 1$$
(20)

where the maximization is over  $a_1, b_1, \ldots, a_d, b_d \in \mathbb{R}$ . We show that this problem can be cast as a complex SDP which has the following form:

$$\min \qquad g^T x 
\text{s.t.} \qquad x_1 G_1 + \dots + x_m G_m + H \succeq 0$$
(21)

where the minimization is over  $x \in \mathbb{R}^m$ . Here,  $g \in \mathbb{R}^m$ , and  $G_1, \ldots, G_m, H$  are complex Hermitian matrices. Note that a complex SDP can always be cast as a real SDP in which  $G_1, \ldots, G_m, H$  are real symmetric matrices.

Note that we can rewrite the objective function as follows:

min 
$$-\lambda$$
s.t. 
$$\sum_{j=1}^{d} (a_j^2 + b_j^2) \le 1$$

$$\sum_{i=1}^{d} (a_j A_j + b_j B_j) \ge \lambda I$$

$$(22)$$

where the maximization is over  $a_1, b_1, \ldots, a_d, b_d, \lambda \in \mathbb{R}$ . Next, we convert this inequality constraint to a positive semidefinite constraint. Let  $c = \sqrt{\sum_{j=1}^{d} (a_j^2 + b_j^2)}$ . Consider the matrix

$$C = \begin{bmatrix} 1 & c \\ c & 1 \end{bmatrix}$$

which has eigenvalues  $1 \pm c$ . Thus, the constraint  $c \le 1$  is equivalent to the constraint  $C \succeq 0$ . Note that  $C \oplus I_{2d-1}$  is unitarily similar to

$$a_1F_1 + \dots + a_dF_d + b_1F_{d+1} + \dots + b_dF_{2d} + I_{2d+1}$$

where  $F_j = E_{j,2d+1} + E_{2d+1,j}$  and  $E_{i,j}$  is an  $(2d+1) \times (2d+1)$  matrix with one at the (i,j)position. Then, the problem becomes

min 
$$-\lambda$$
  
s.t.  $a_1F_1 + \dots a_dF_d + b_1F_{d+1} + \dots + b_dF_{2d} + I_{2d+1} \succeq 0$   

$$\sum_{j=1}^{d} (a_jA_j + b_jB_j) - \lambda I \succeq 0$$
(23)

where the maximization is over  $a_1, b_1, \ldots, a_d, b_d, \lambda \in \mathbb{R}$ . This is in the SDP form (21). Thus, one can apply standard positive semidefinite programming to determine the time-energy cost of a general quantum channel given in Eq. (6).

### 5 Mathematical remarks

• We may replace  $K_1$  by  $e^{i\theta_1}K_1$  without affecting the quantum channel. Thus, we can select  $\theta_1 \in [0, 2\pi)$  to maximize the smallest eigenvalue of  $e^{i\theta_1}K_1 + e^{-i\theta_1}K_1^{\dagger}$ . To this end, we can use the numerical range of  $K_1$  defined as

$$W(K_1) = \{ \langle x | K_1 | x \rangle : | x \rangle \in \mathbb{C}^n, \langle x | x \rangle = 1 \}.$$

This is a compact convex set in  $\mathbb{C}$ , and can be obtained as the intersection of the half spaces

$$Q_{\theta_1} = \left\{ \mu \in \mathbb{C} : e^{i\theta_1} \mu + e^{-i\theta_1} \bar{\mu} \ge \lambda_{\min}(e^{i\theta_1} K_1 + e^{-i\theta_1} K_1^{\dagger}) \right\}, \quad \theta_1 \in [0, 2\pi).$$

So, maximizing the smallest eigenvalue of  $e^{i\theta_1}K_1 + e^{-i\theta_1}K_1^{\dagger}$  corresponds to finding the half space  $Q_{\theta_1}$  whose intersection with the unit disk has the smallest area.

• A heuristic approach to upper bound Eq. (6) is as follows. We separately consider  $v_jK_j, j=1,\ldots,d$  and let  $v_j=c_j\exp(i\theta_j)$  where  $c_j\in\mathbb{R}_+$ . Choose  $\theta_j\in[0,2\pi)$  to maximize the smallest eigenvalue  $\sigma_j$  of  $e^{i\theta_j}K_j+e^{-i\theta_j}K_j^{\dagger}$ . This is equivalent to rotating the numerical range  $W(K_j)$  so that the left support line is as close to the right side as possible. Then choose a nonnegative unit vector  $(c_1,\ldots,c_d)$  to maximize  $\sum_{j=1}^d c_j\sigma_j$ . If  $K_{\mathbf{v}}=\sum_{j=1}^d c_j\exp(i\theta_j)K_j$ , then  $\lambda_{\min}\left(K_{\mathbf{v}}+K_{\mathbf{v}}^{\dagger}\right)\geq\sum_{j=1}^d c_j\sigma_j$ . Thus,  $\|\mathcal{K}\|_{\max}\leq\cos^{-1}(\sum_{j=1}^d c_j\sigma_j/2)$ .

### 6 Conclusions

The physical meaning of the time-energy cost is its relation with the channel fidelity [5]. In this paper, we show that the time-energy cost of any general quantum channel is given by Eq. (6). It has closed formulas for special channels. For general channels, the problem of finding the time-energy cost can be formulated as an SDP which can be solved efficiently on computers.

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